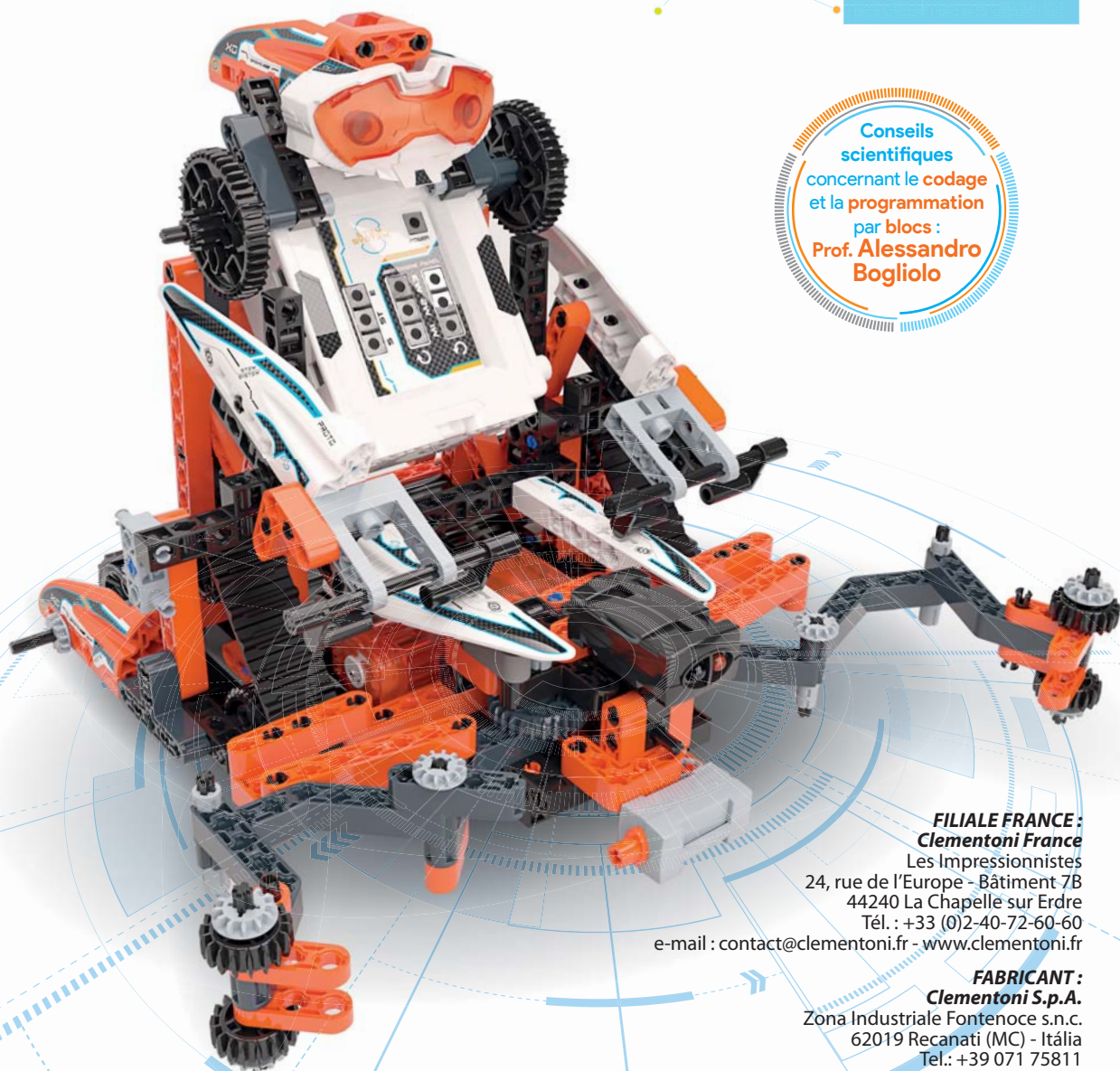


RoboMaker[®]

le laboratoire de robotique éducative **pro**



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Les Impressionnistes

24, rue de l'Europe - Bâtiment 7B

44240 La Chapelle sur Erdre

Tél. : +33 (0)2-40-72-60-60

e-mail : contact@clementoni.fr - www.clementoni.fr

FABRICANT :

Clementoni S.p.A.

Zona Industriale Fontenoce s.n.c.

62019 Recanati (MC) - Italia

Tel.: +39 071 75811

www.clementoni.com

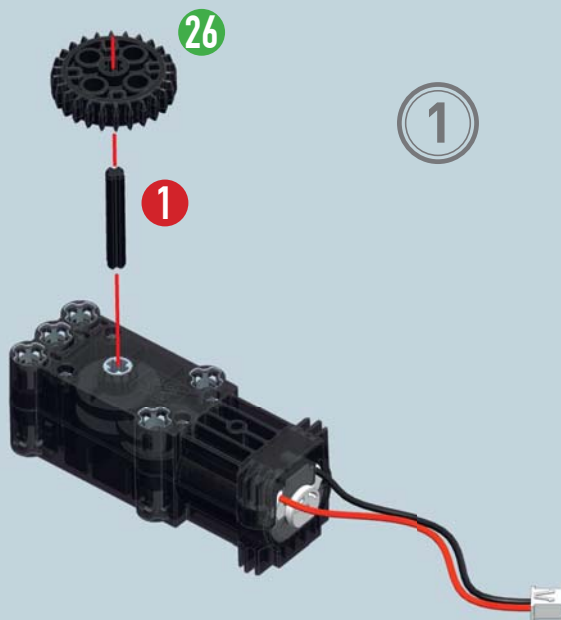
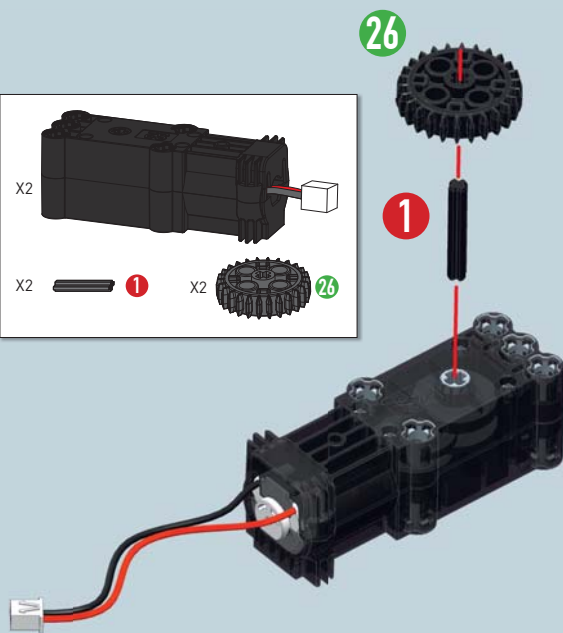
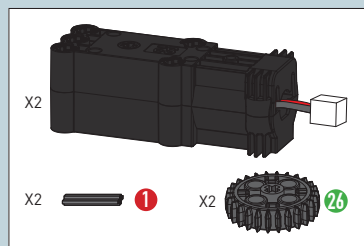


Notice à lire et à conserver pour toute consultation ultérieure.



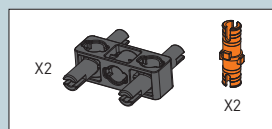
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Assemblage

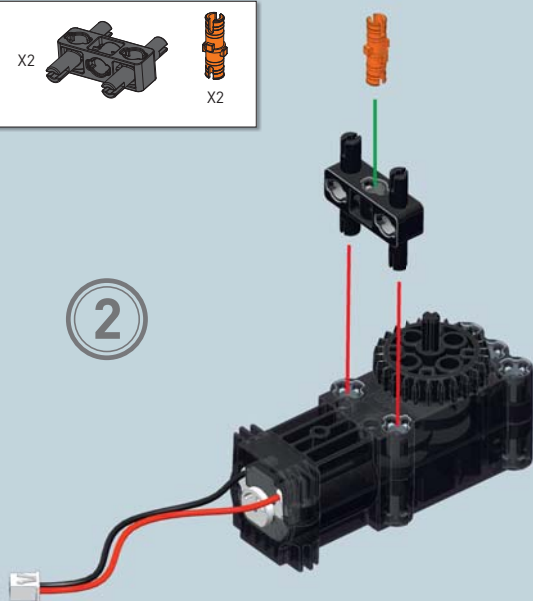


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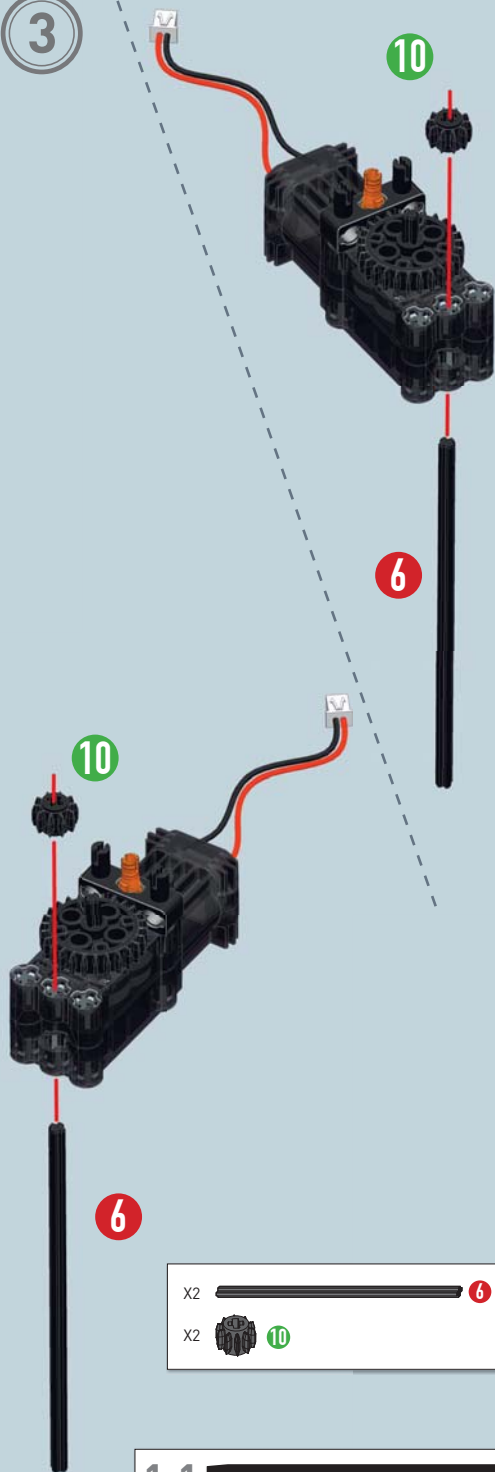
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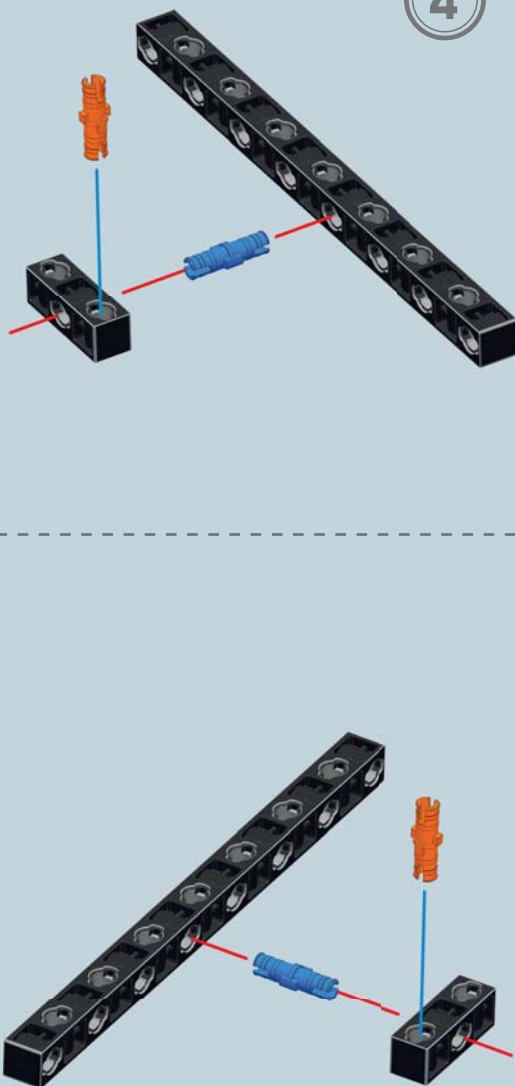








3



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X2		10

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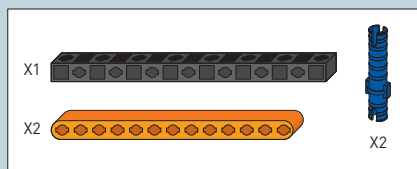


X2		X2			
X2		6	X2		

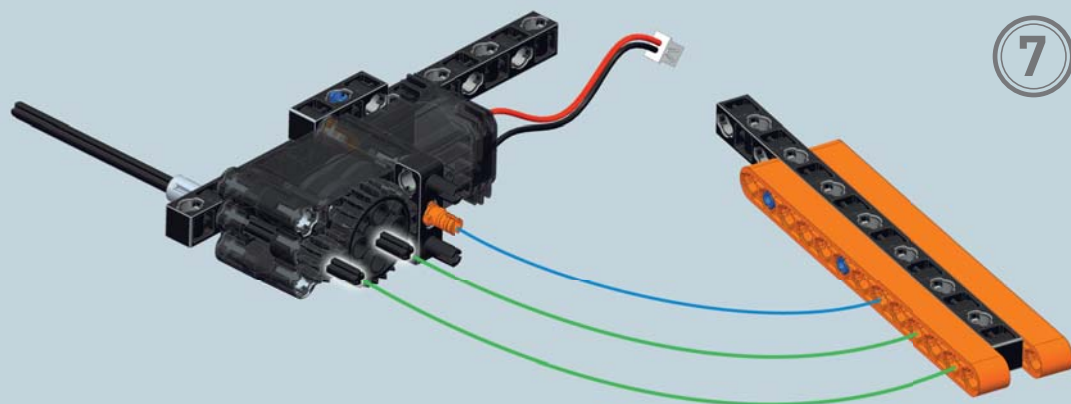
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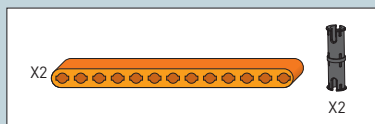
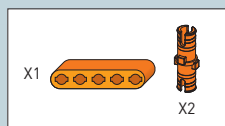
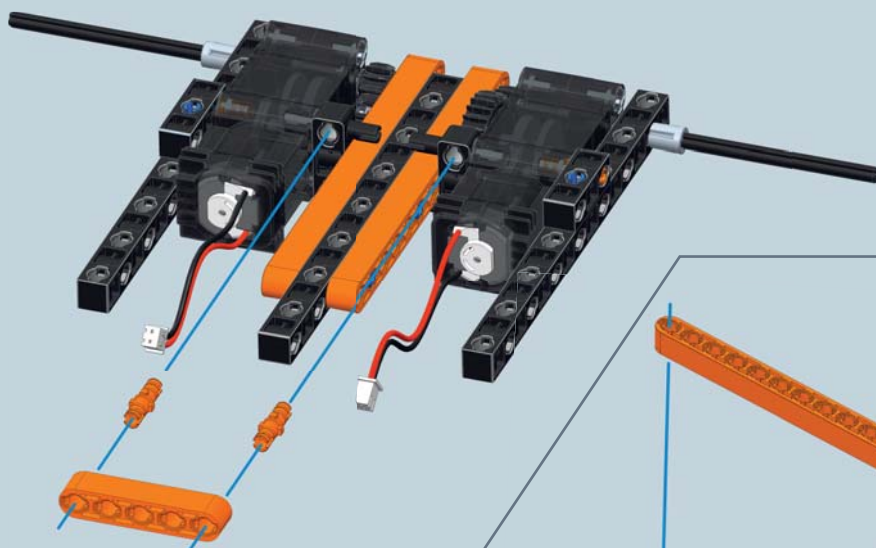
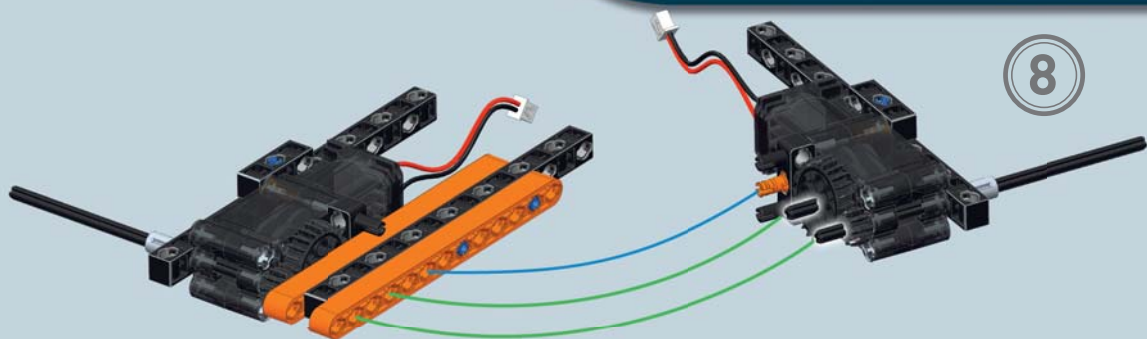
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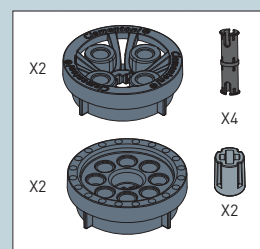
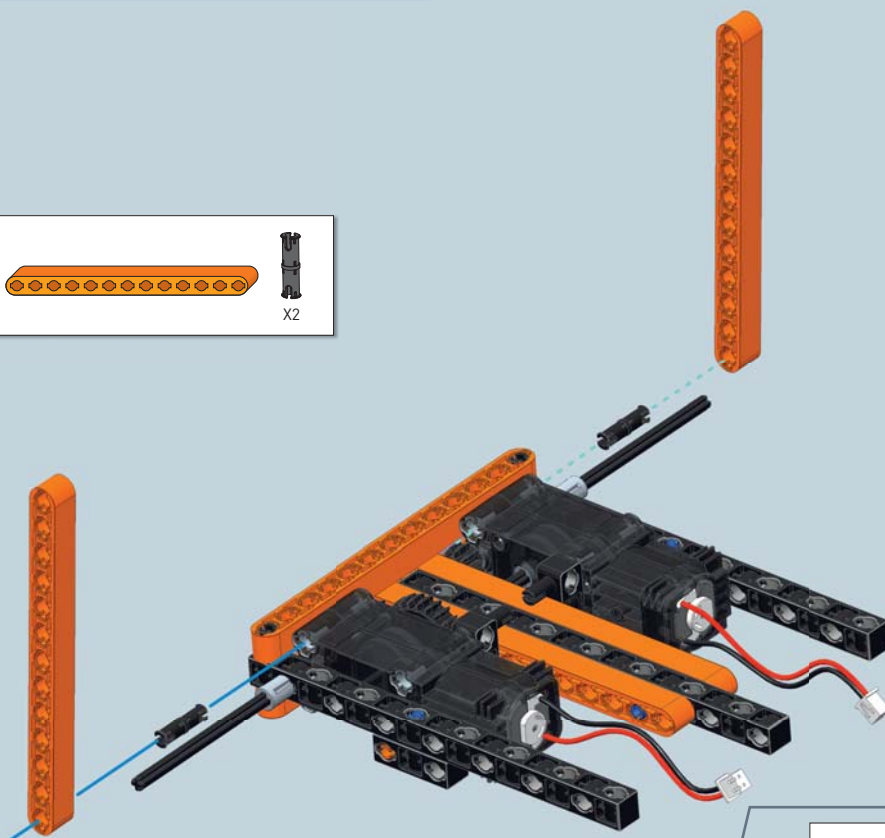
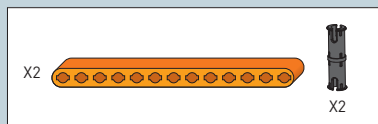
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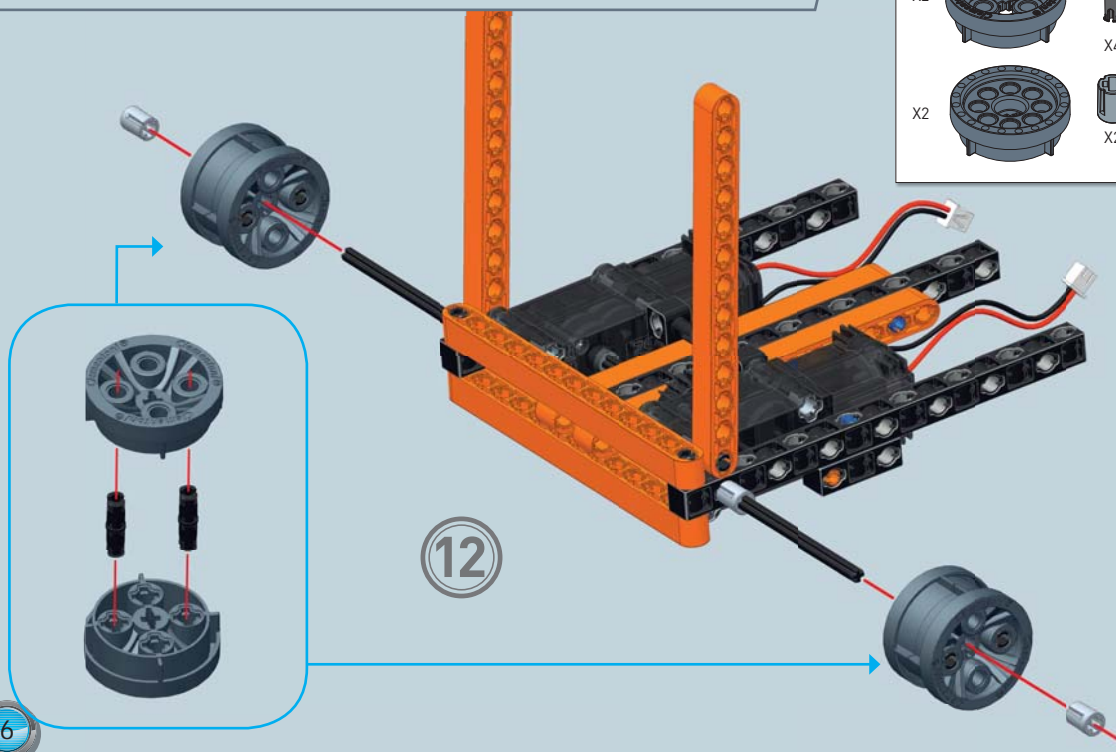
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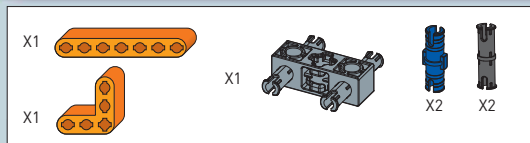
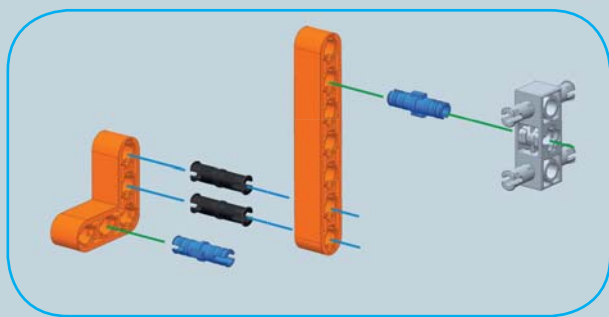


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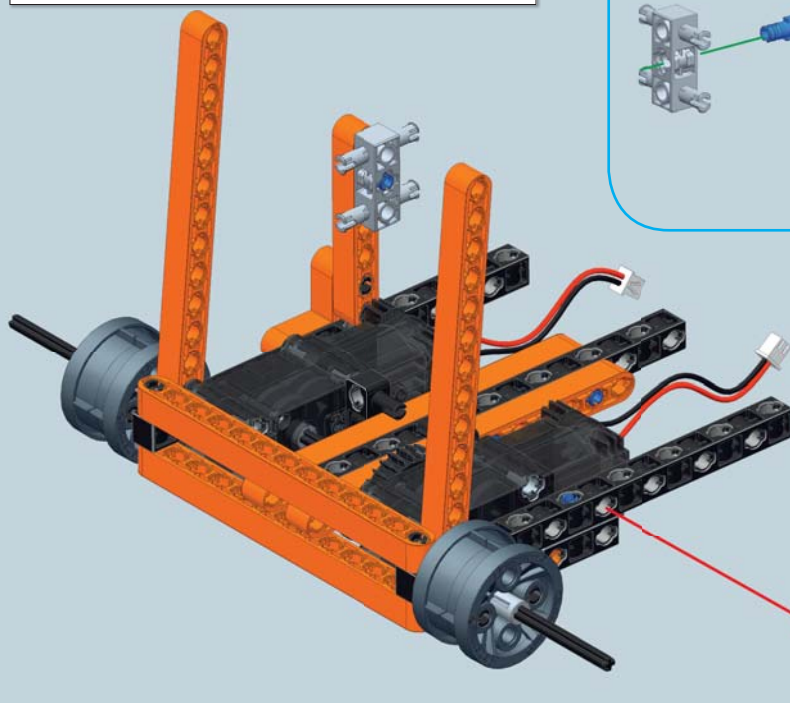
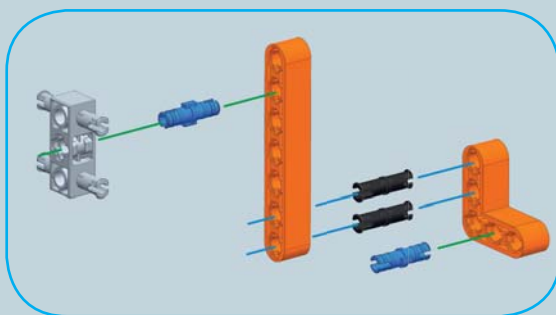
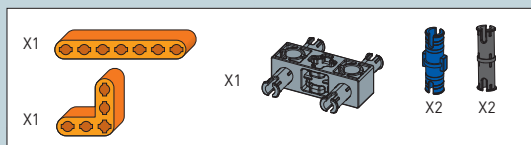
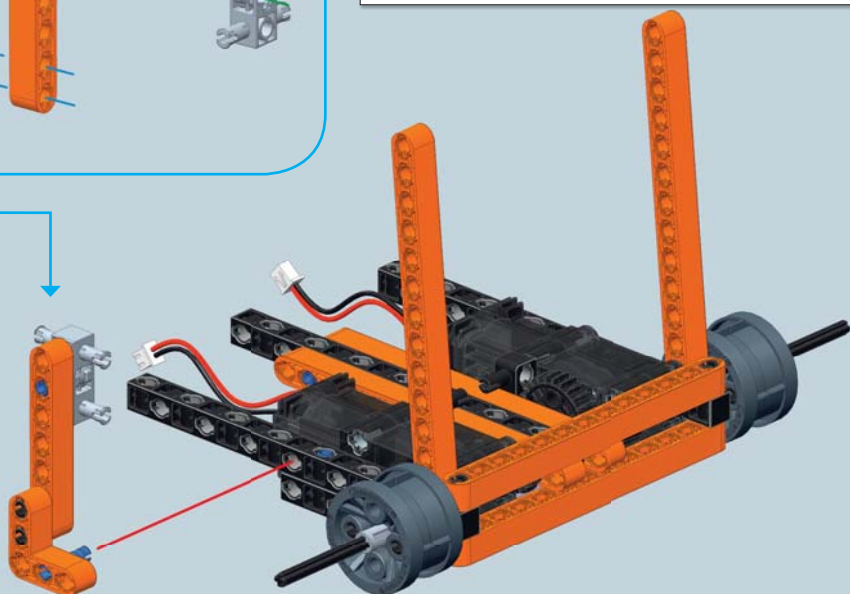


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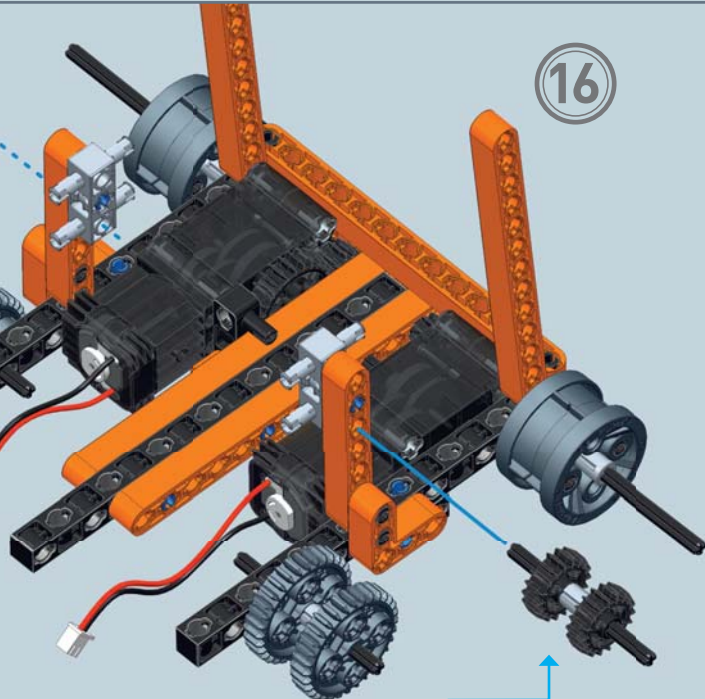
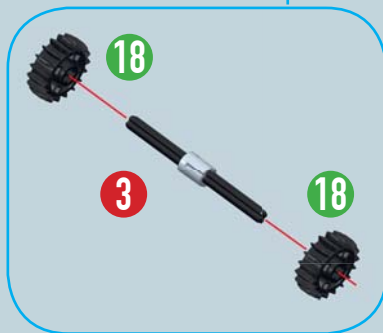
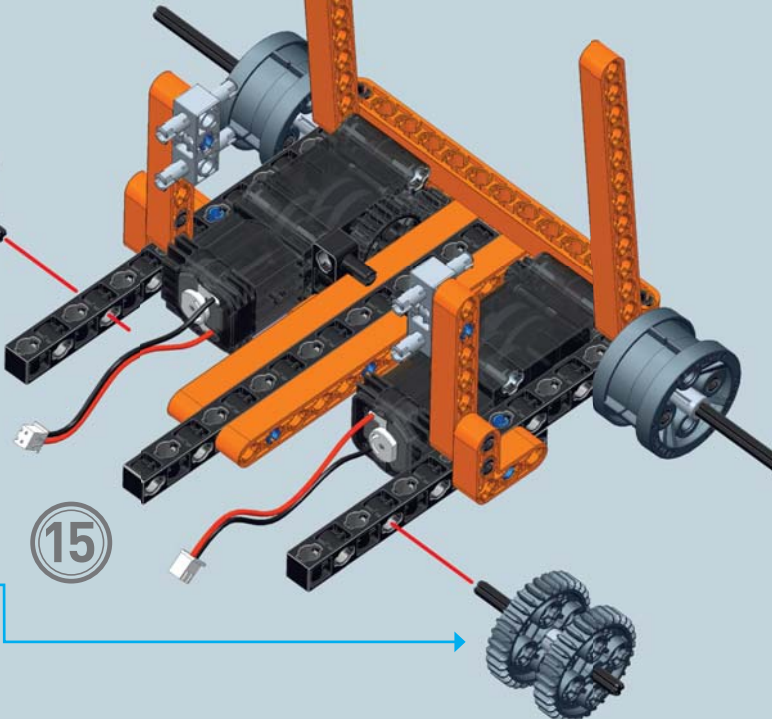
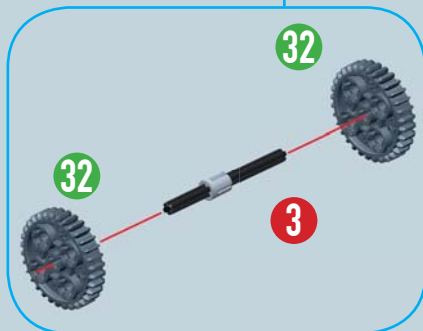
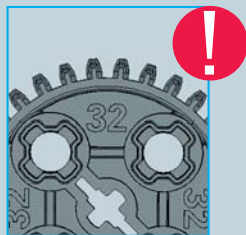
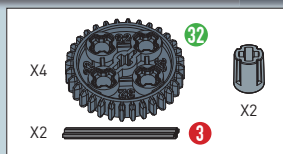


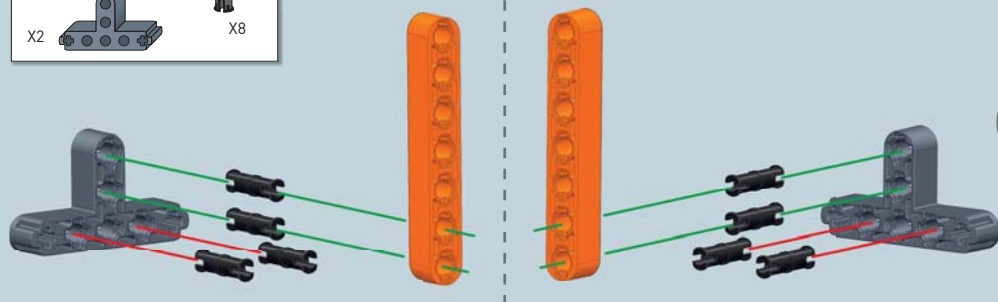
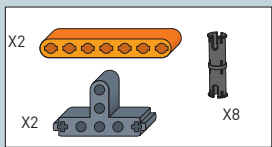


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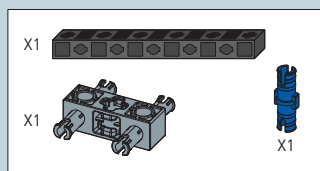
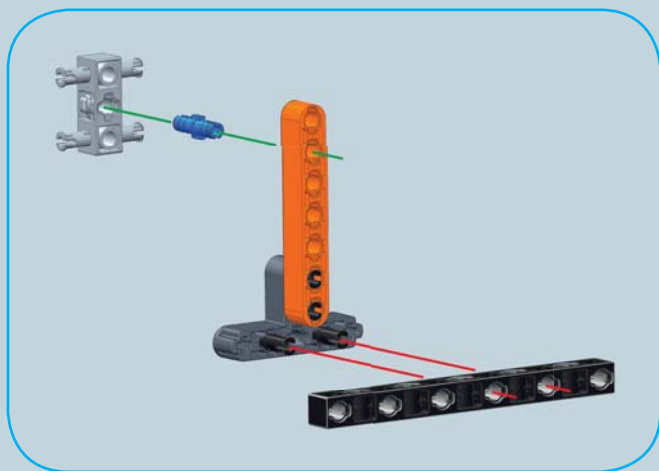
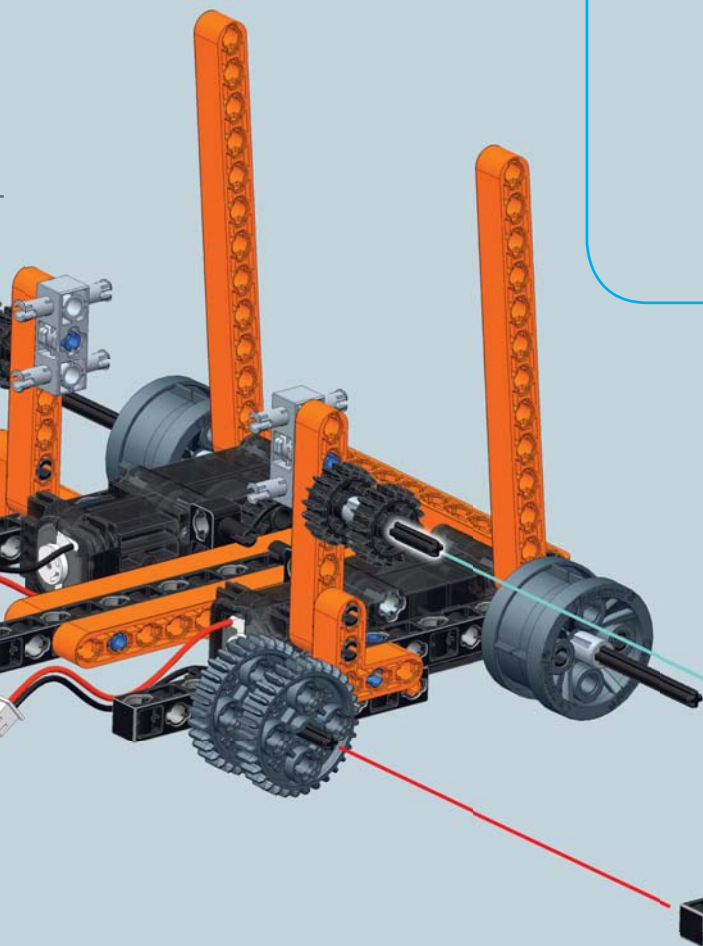
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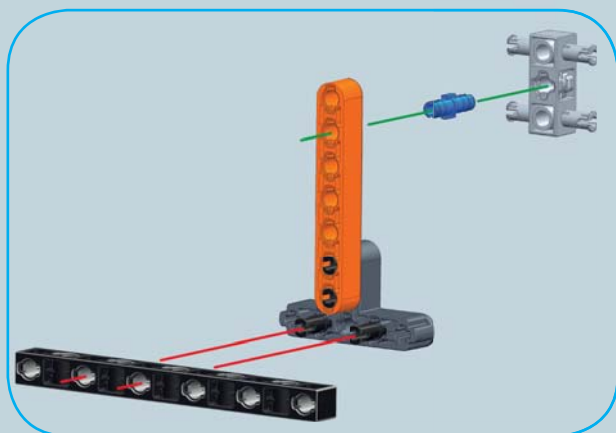




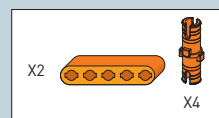
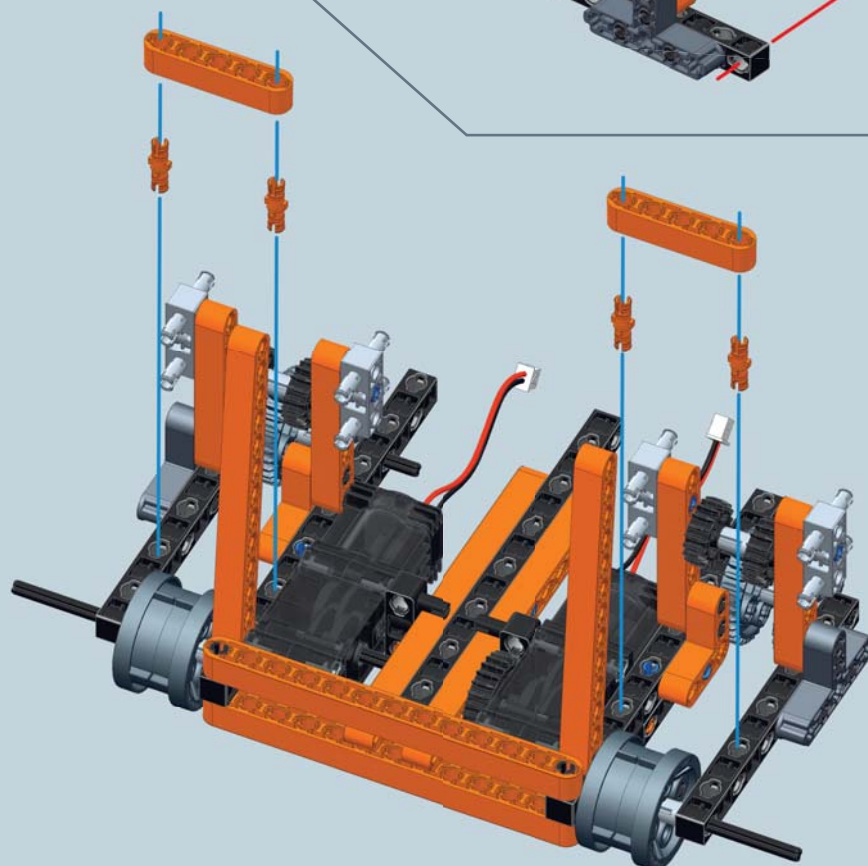
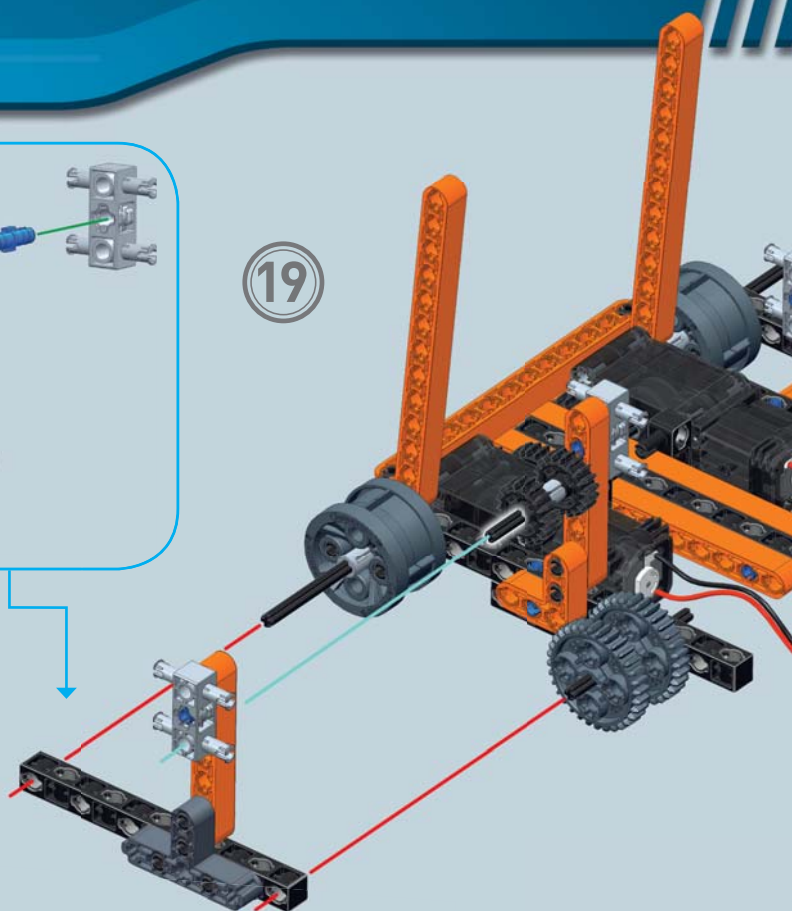
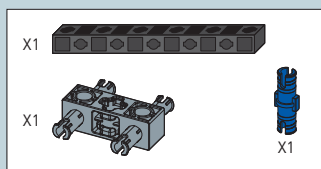
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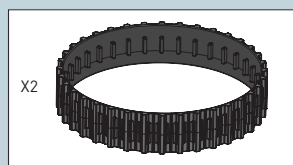
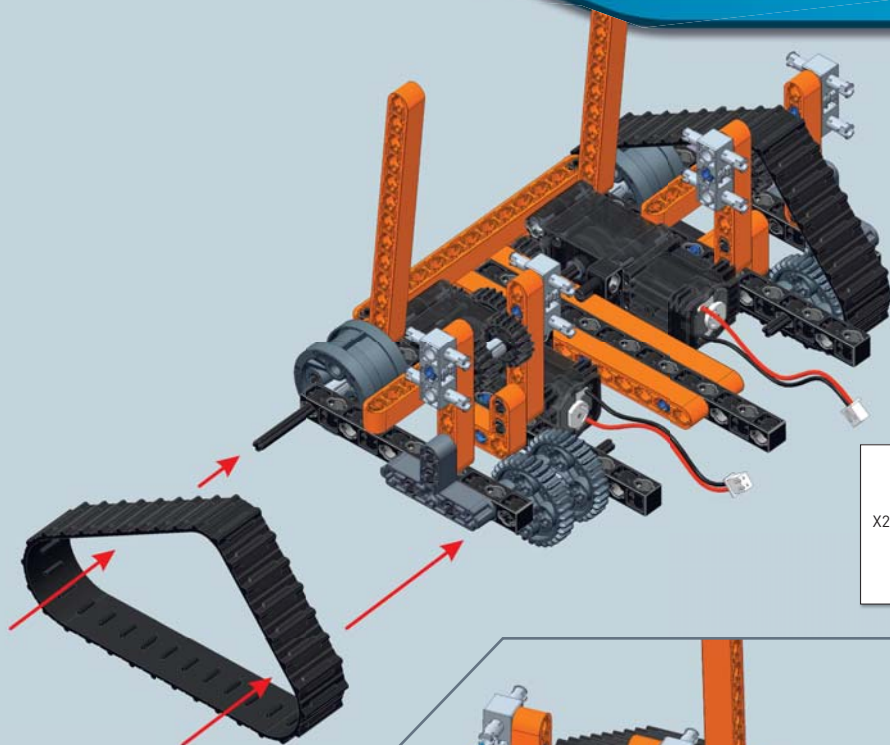


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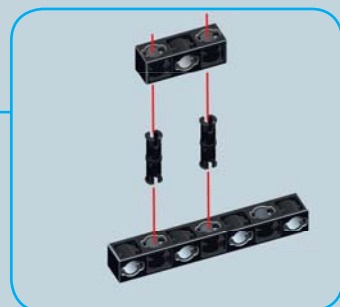
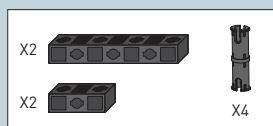
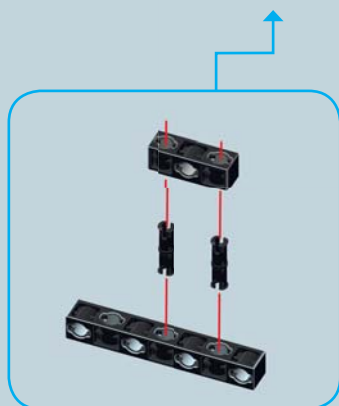
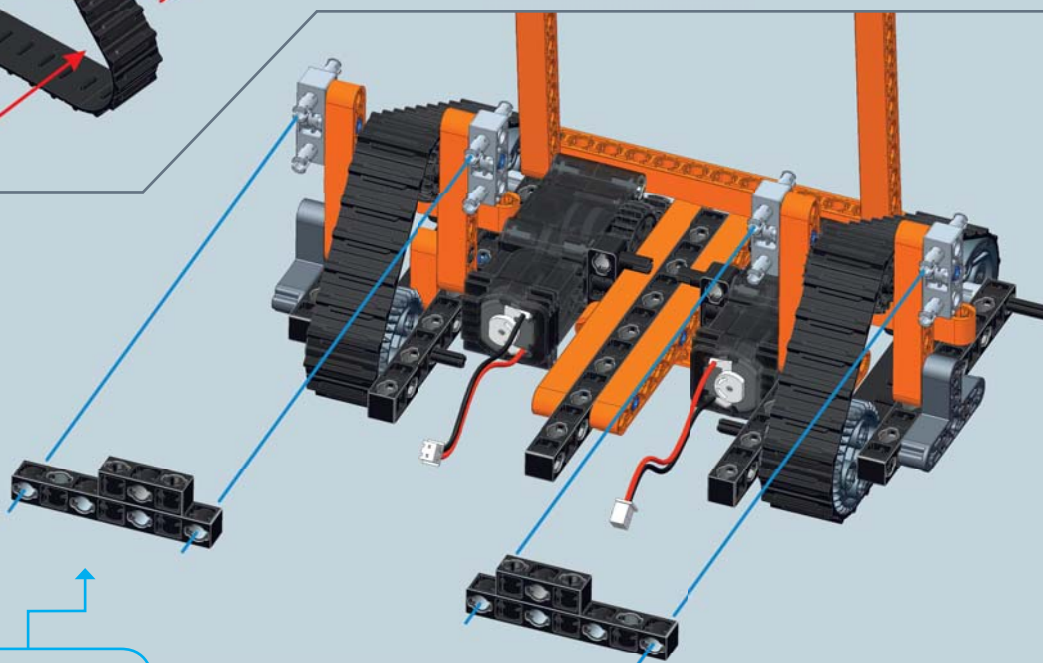


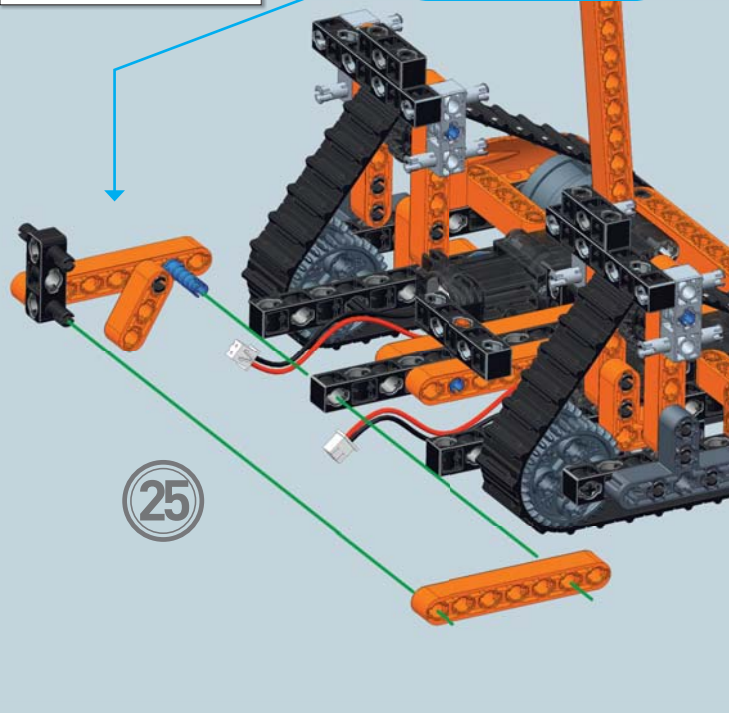
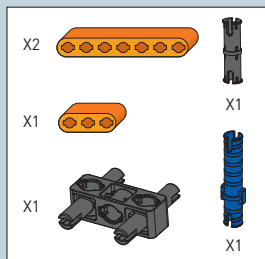
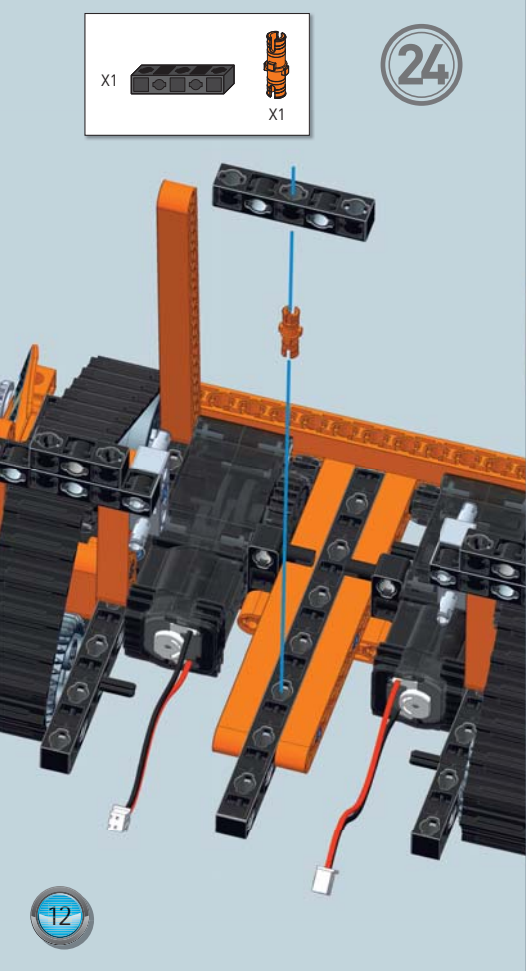
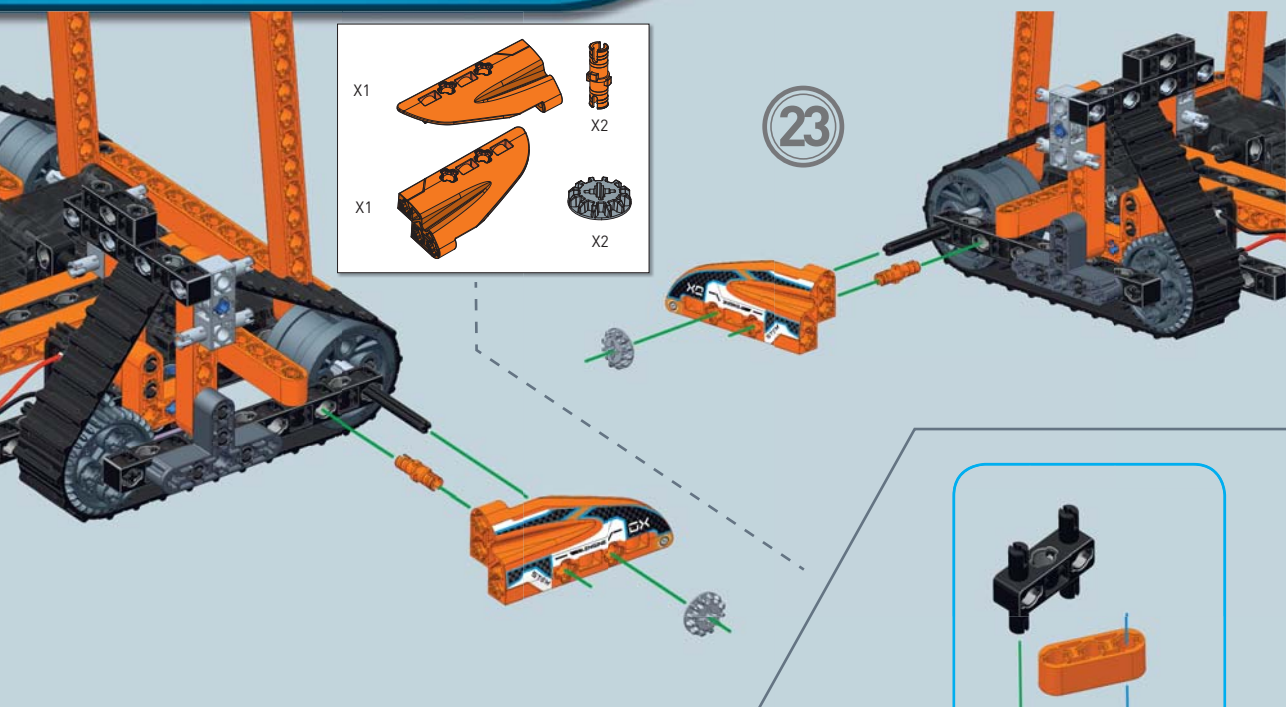
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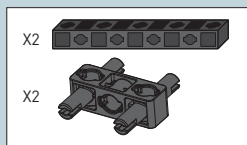
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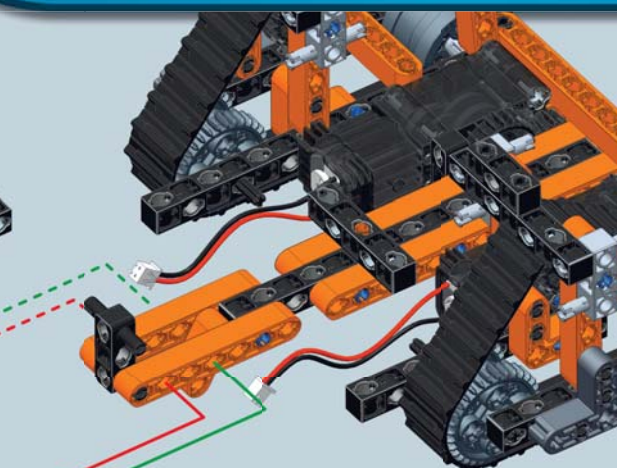
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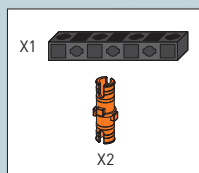




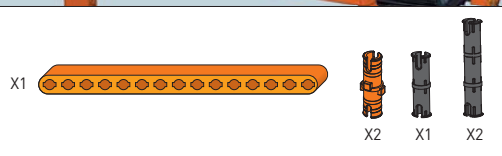
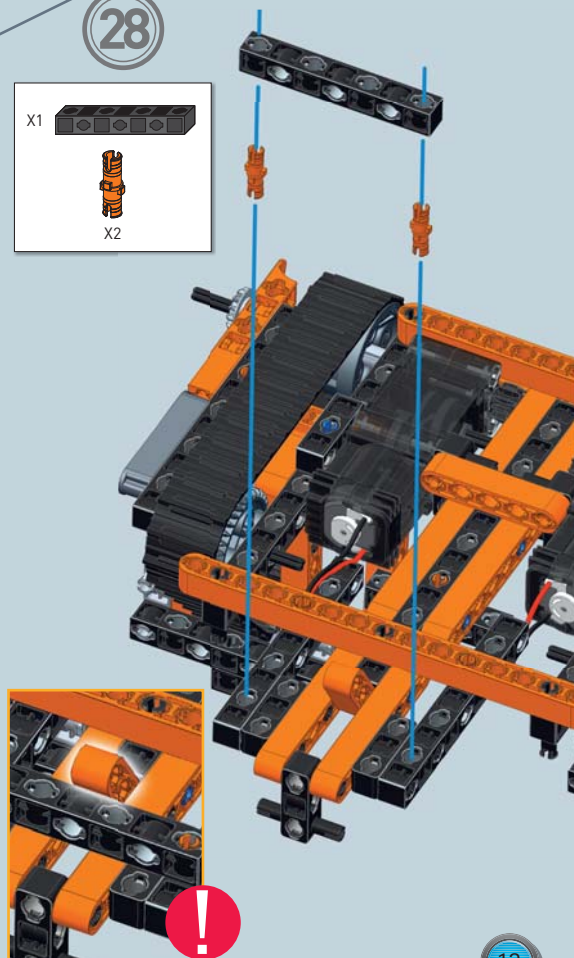
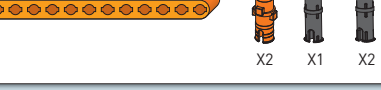
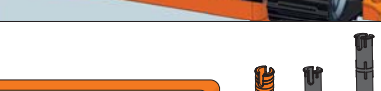
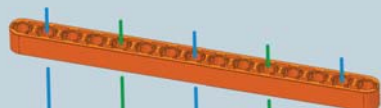
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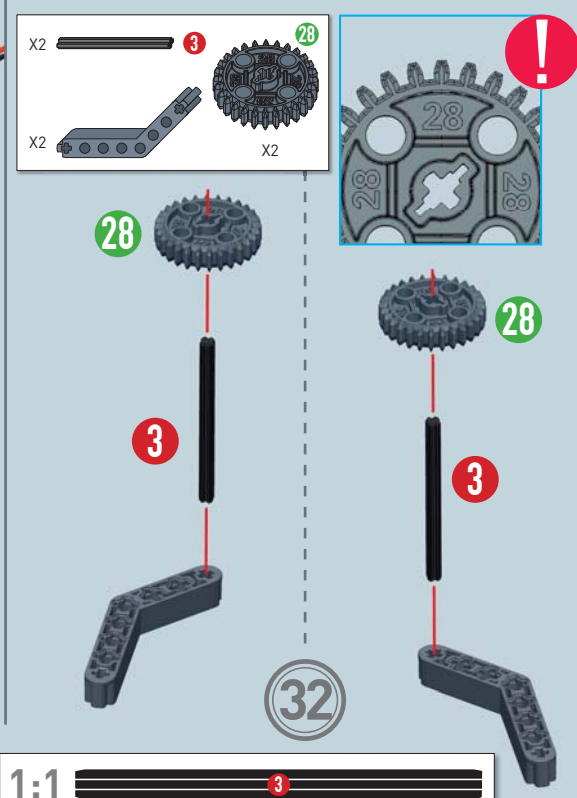
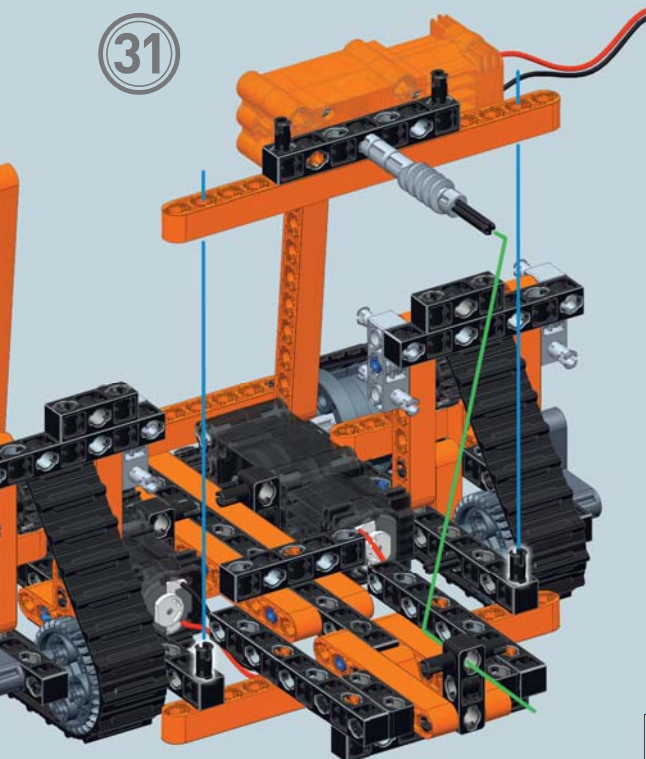
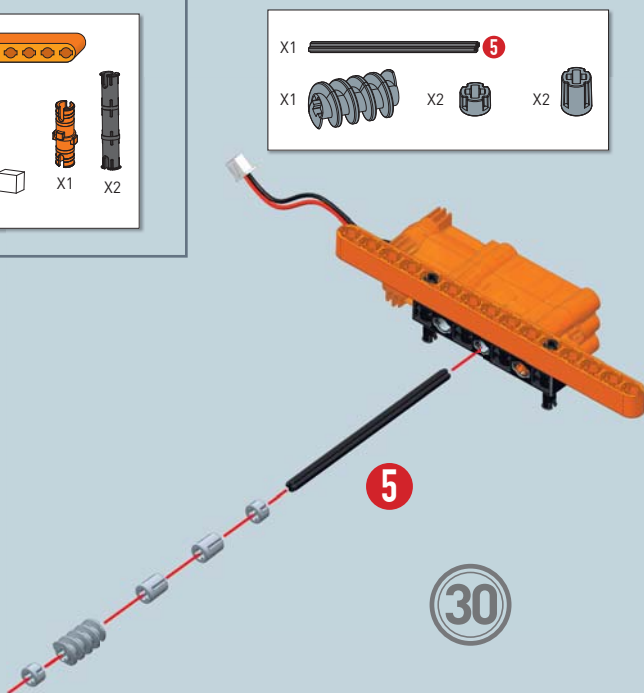
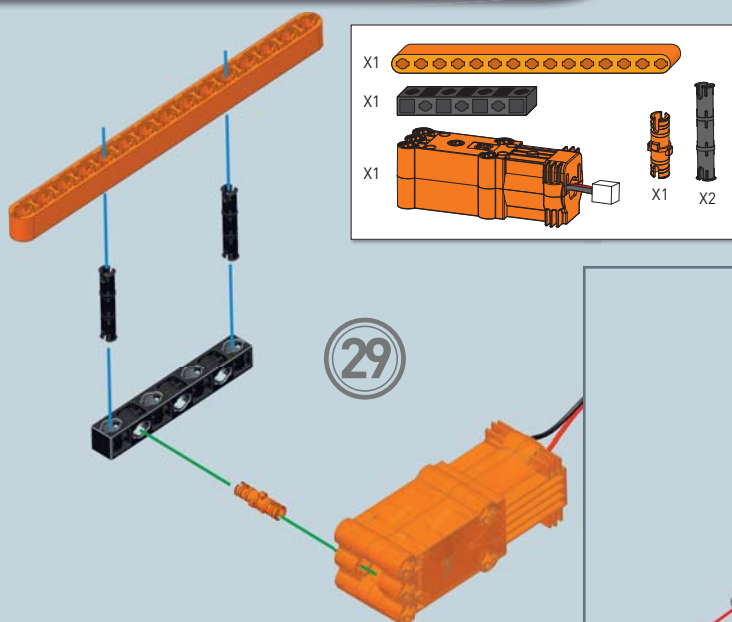


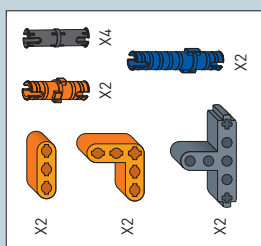
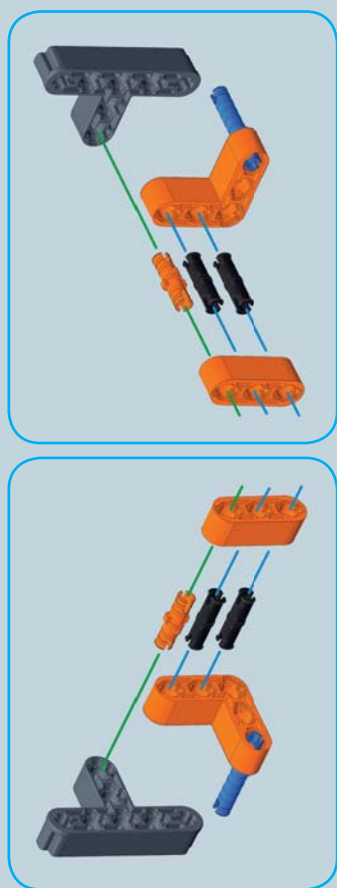
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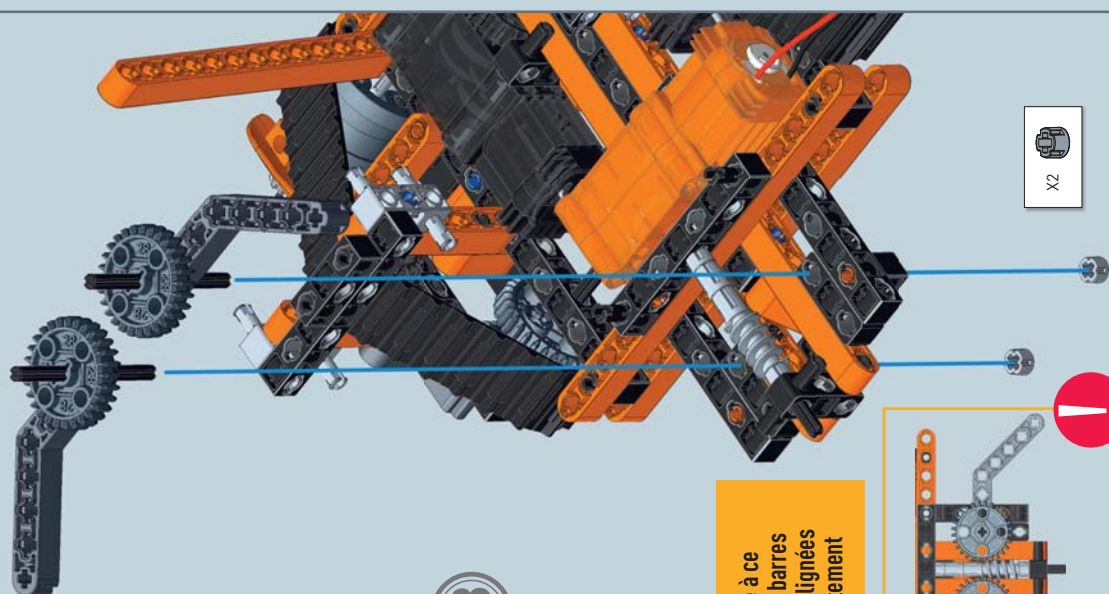
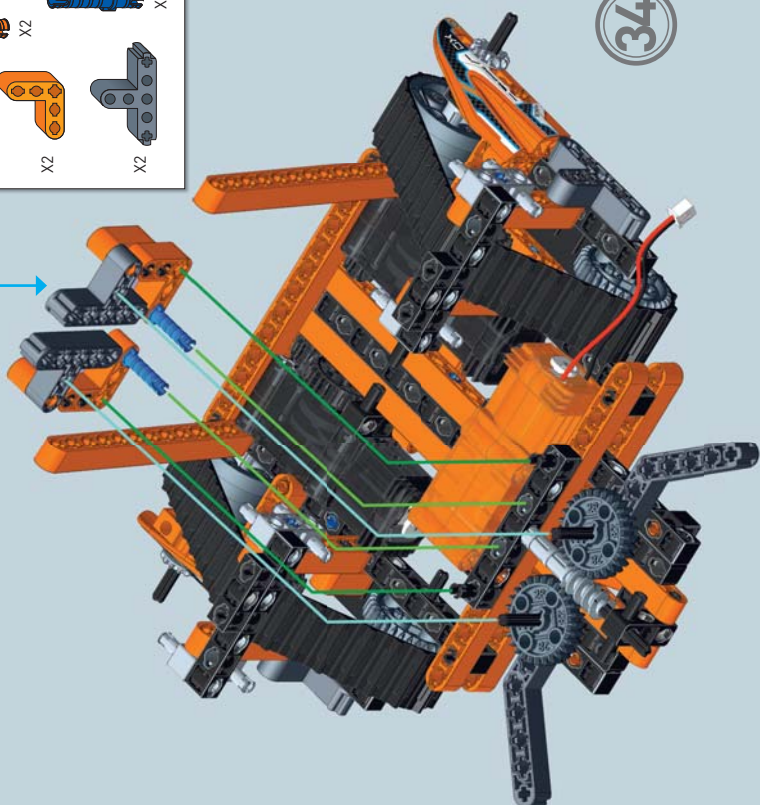
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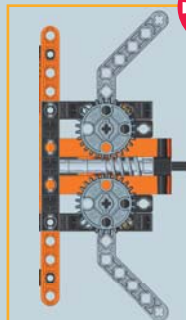




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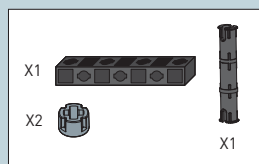


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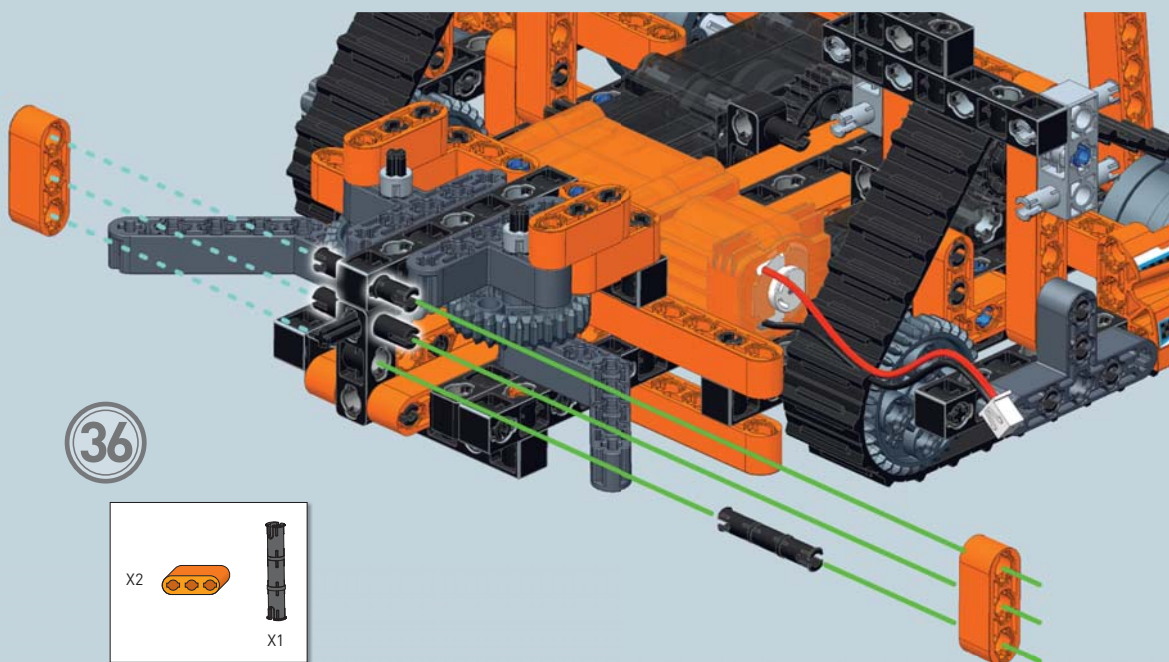
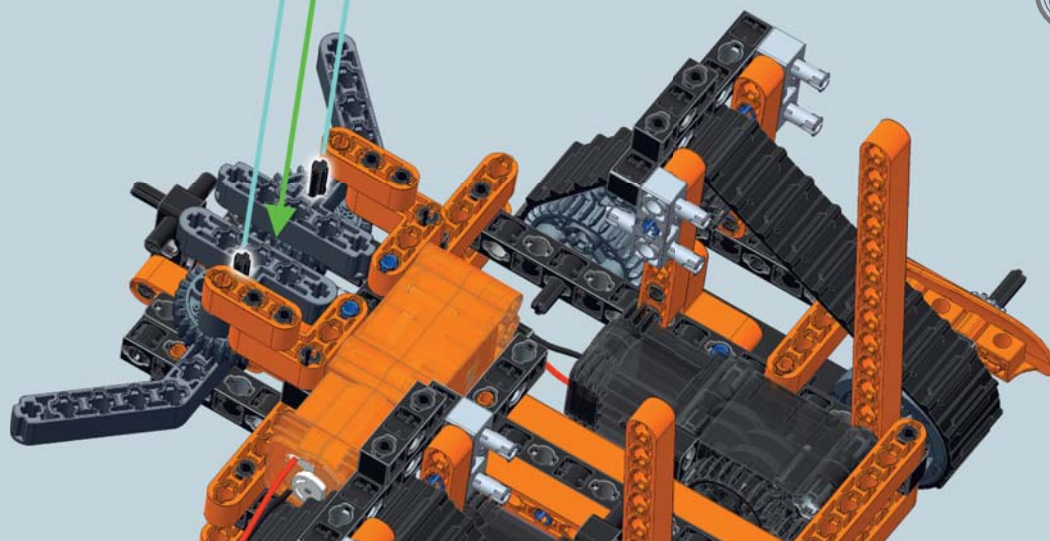


Veille à ce
que les barres
soient alignées
correctement

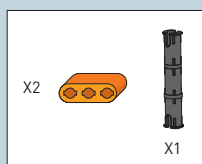
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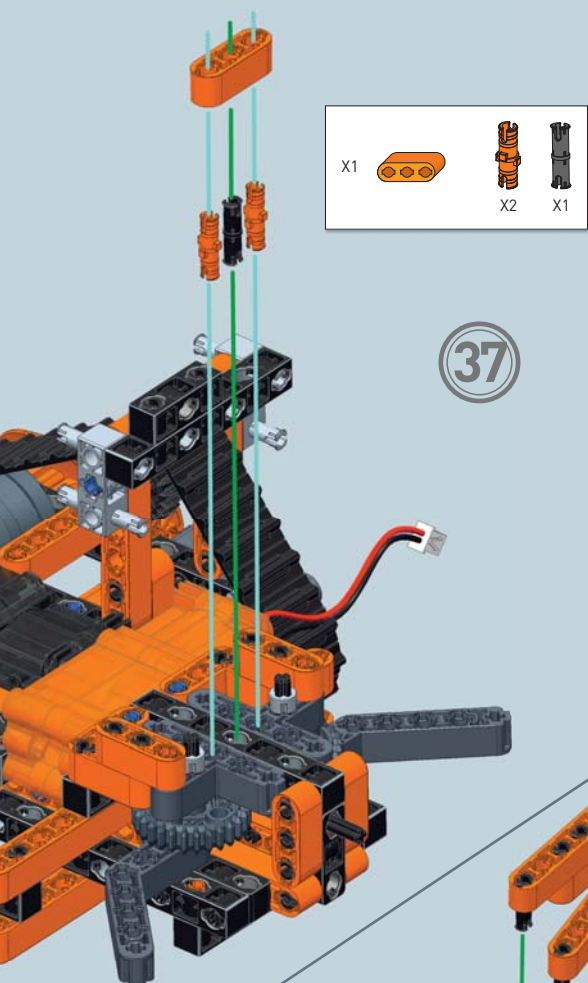


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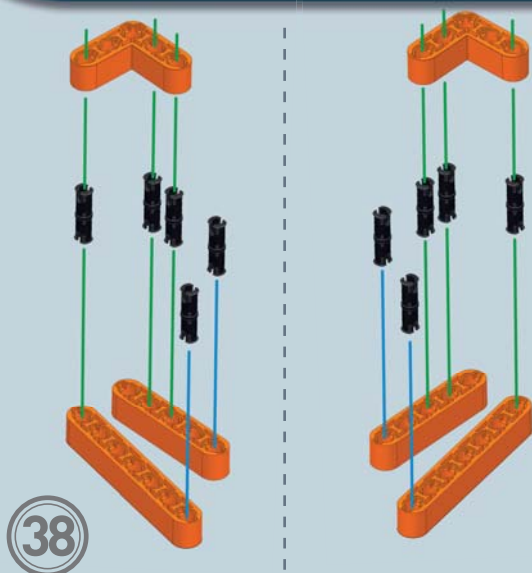


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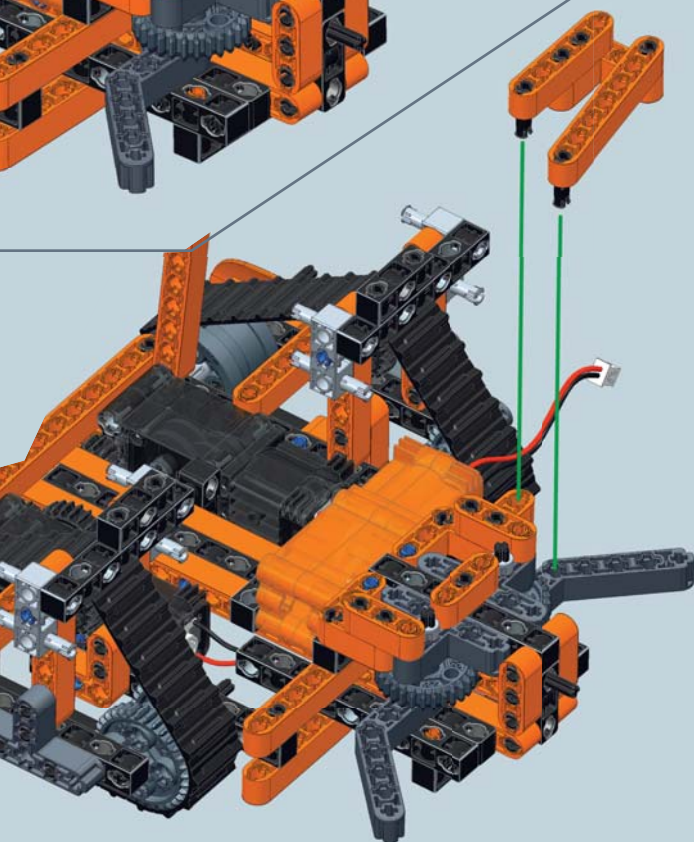




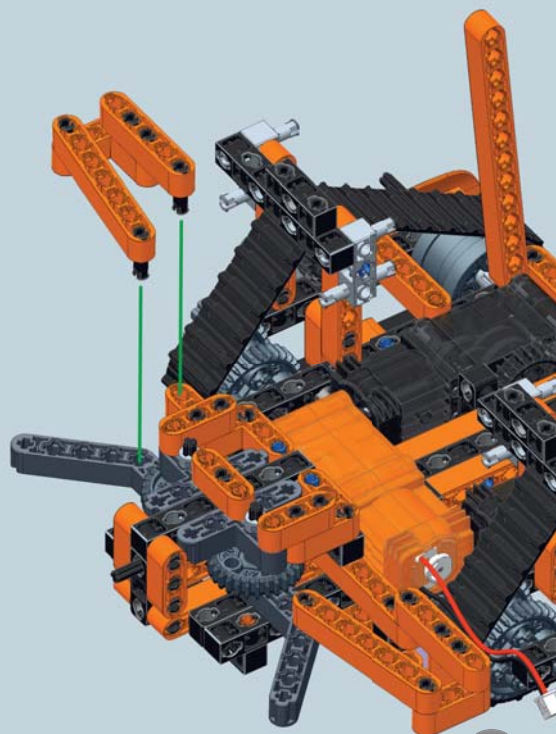
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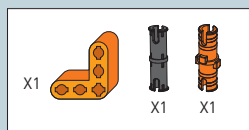
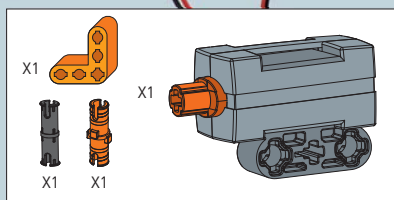
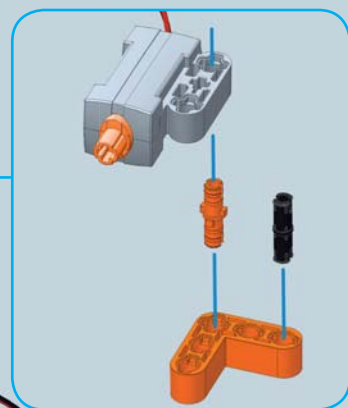
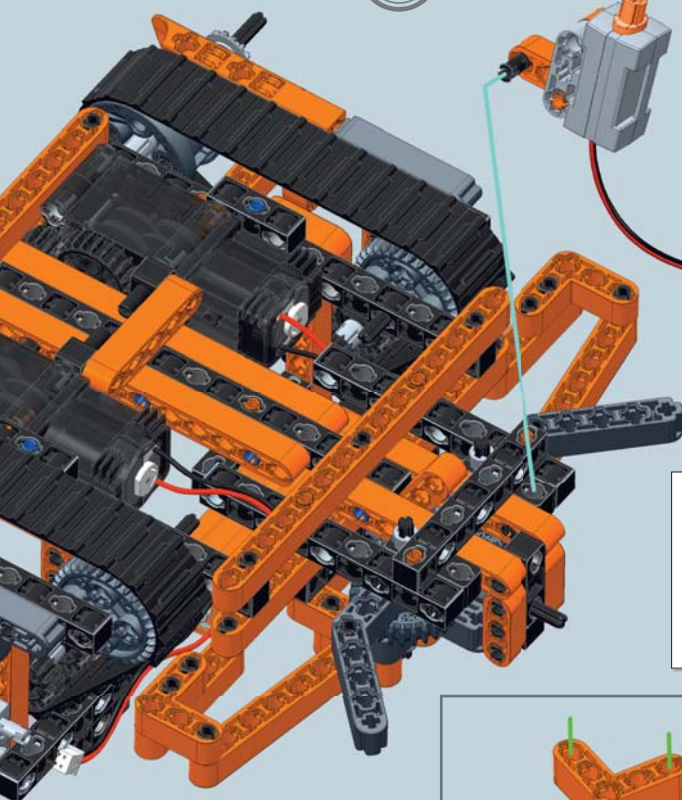
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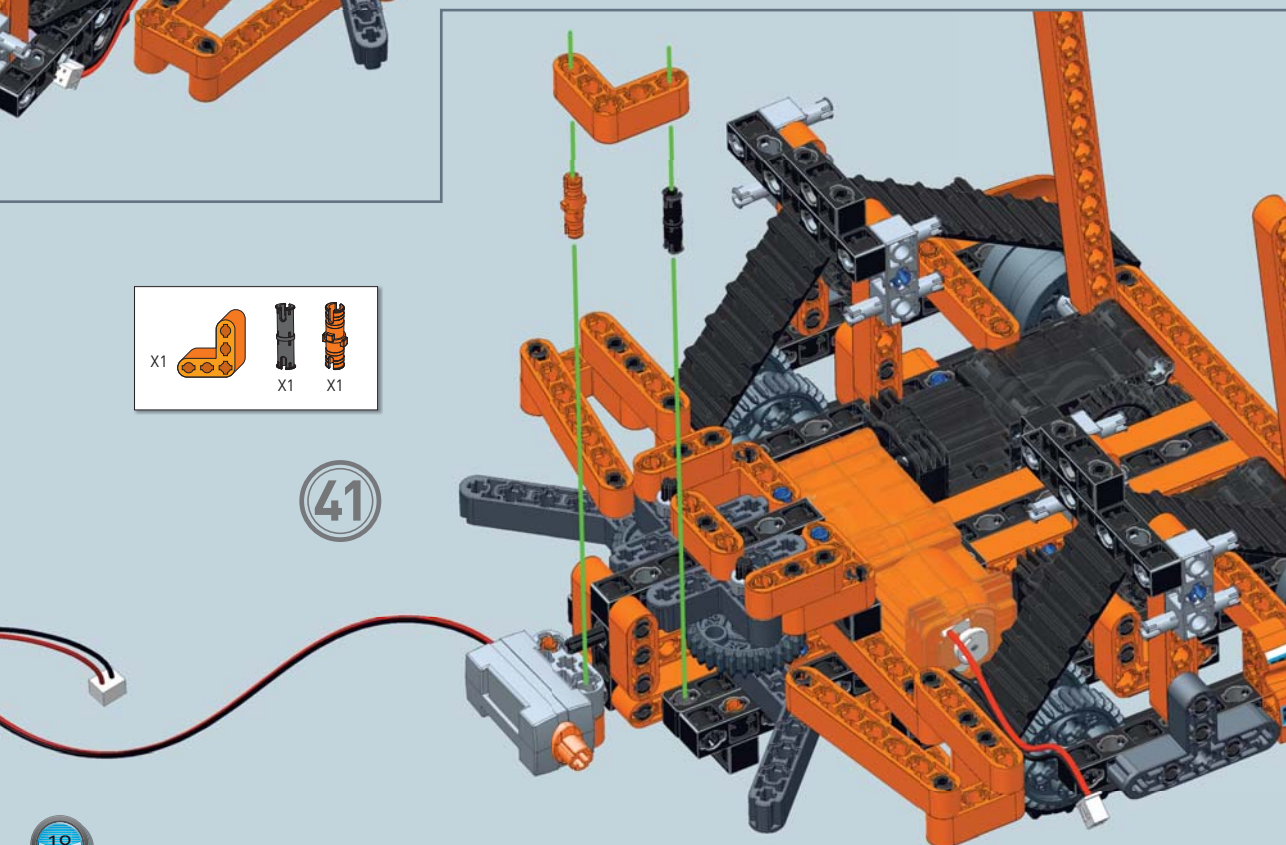
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40



41



1:1

1:1

44

42

43

12

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18

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18

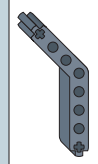


12

X4

18

X4



X4

2

X2

X4

X2

2

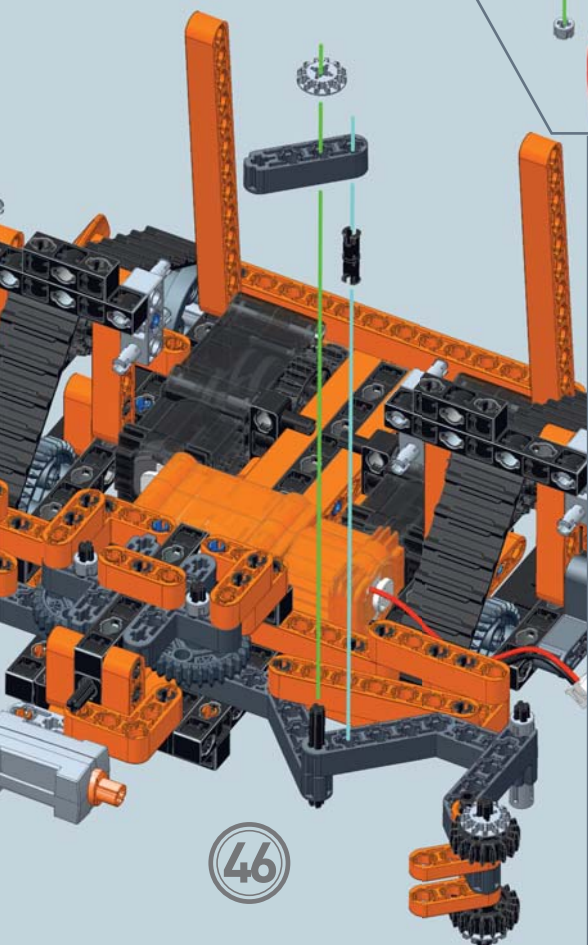
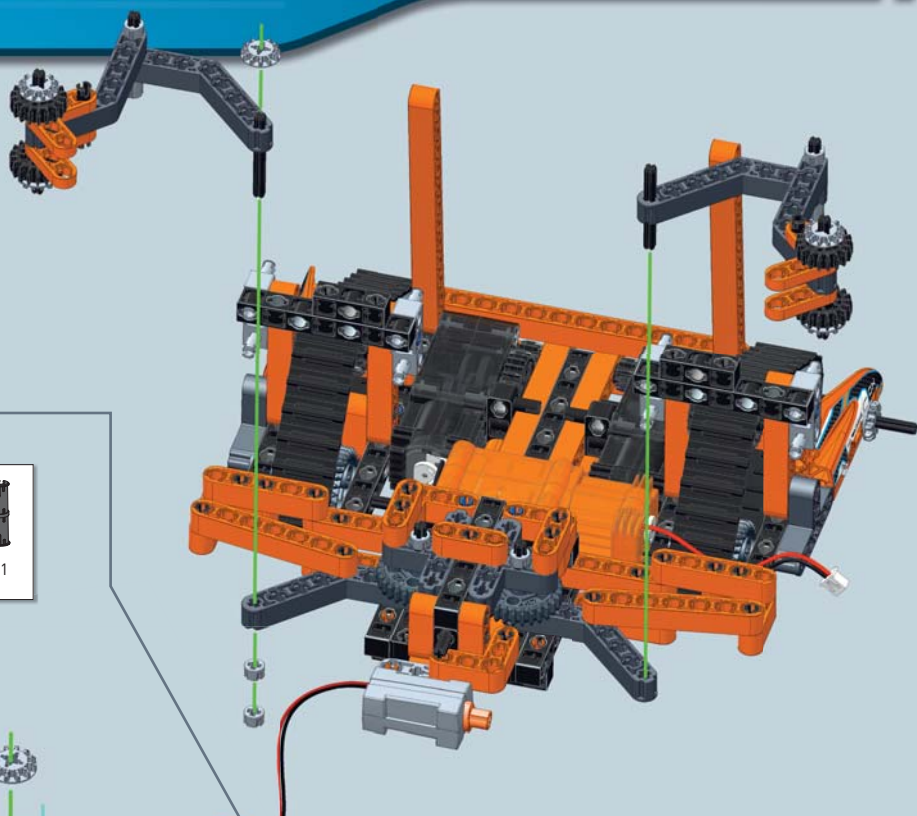
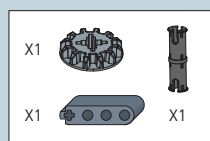
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2

2



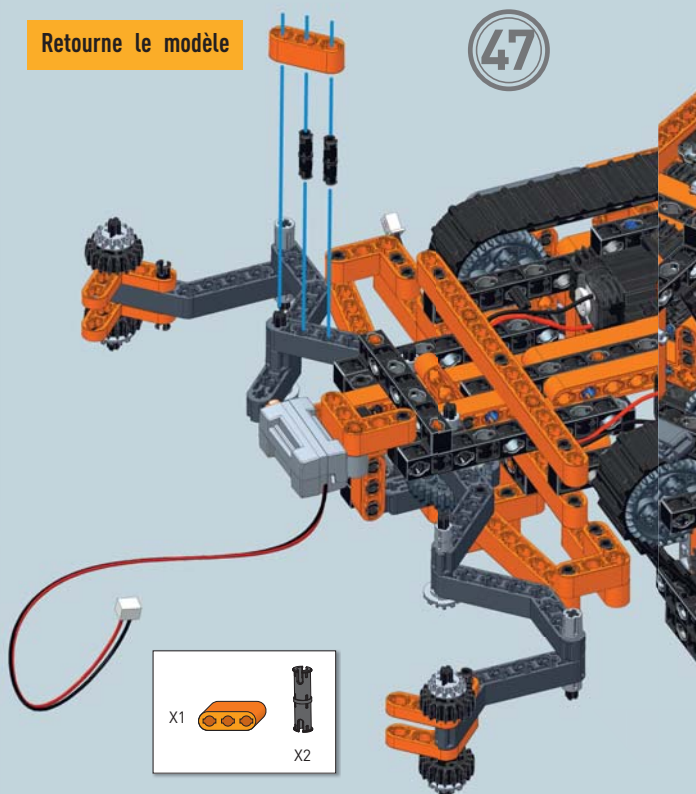
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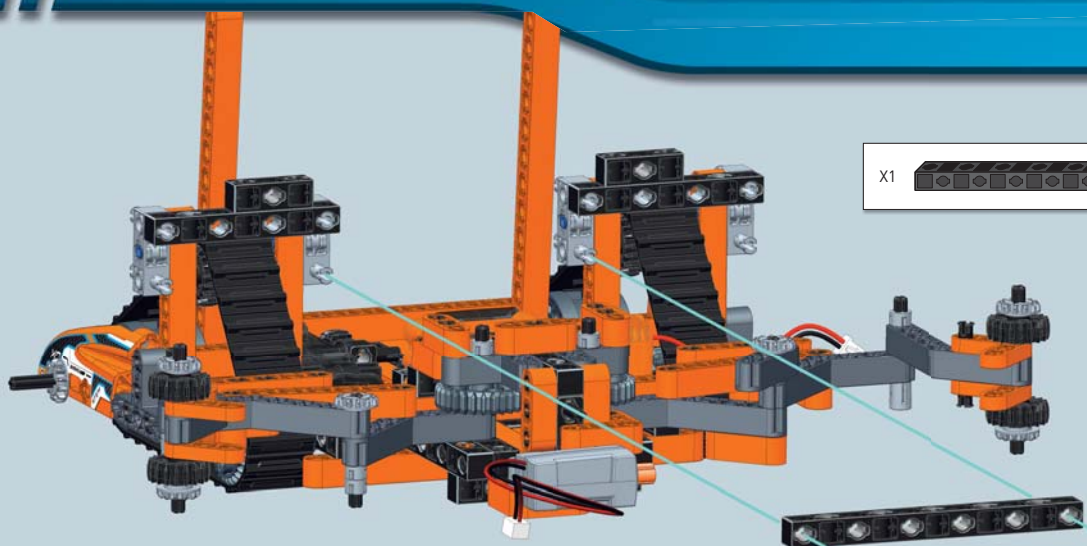


46

Retourne le modèle

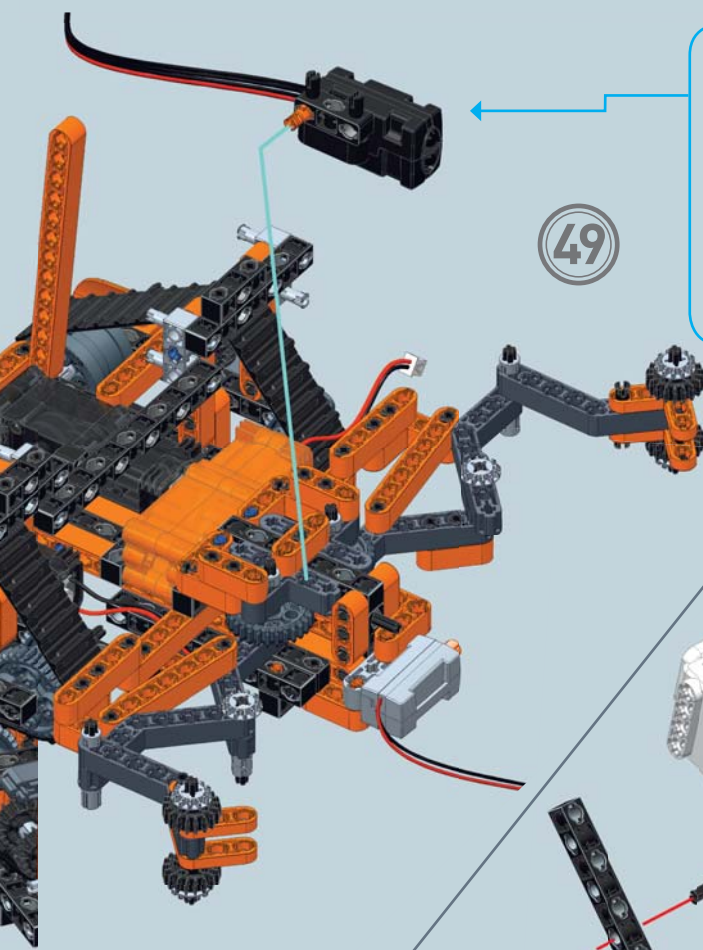
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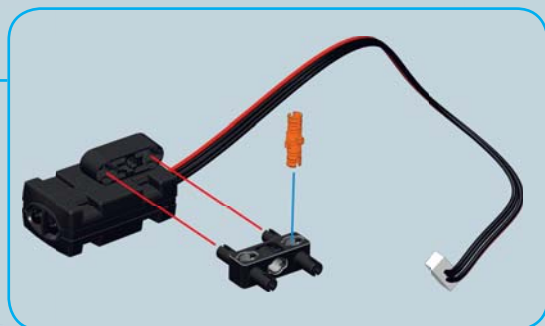


X1

48



49

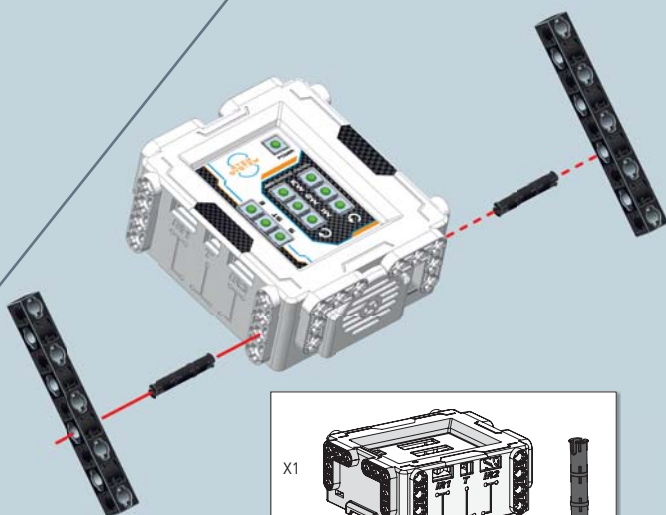


X1

X1

X1

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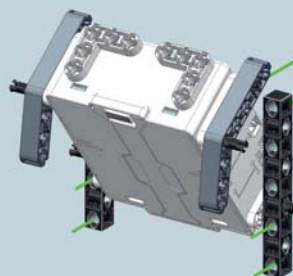
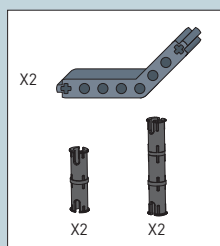
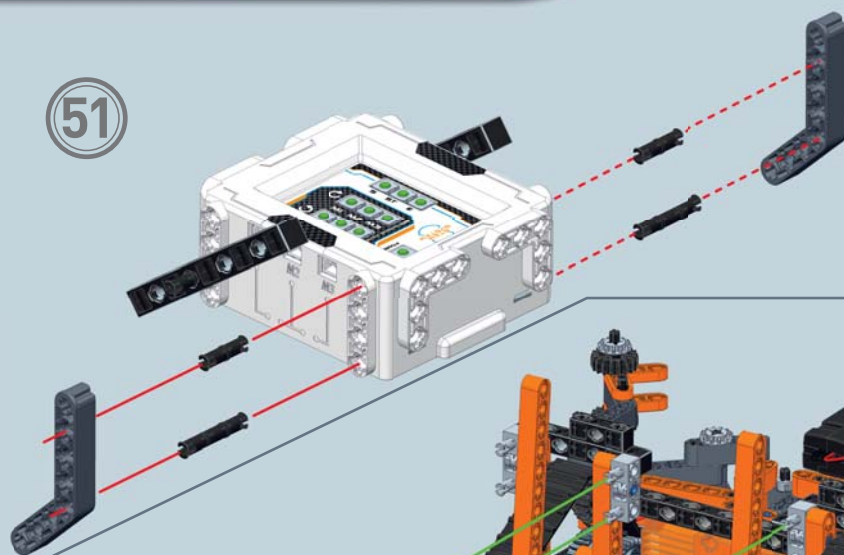
X1

X2

X2

21

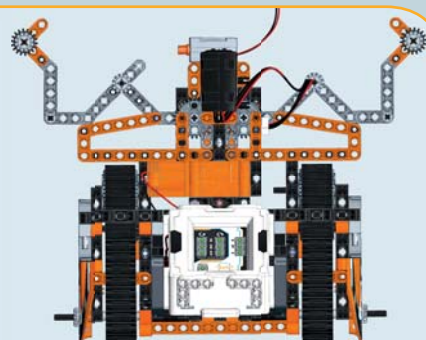
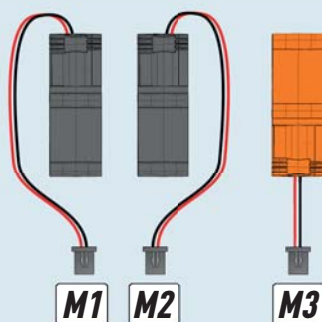
51



52

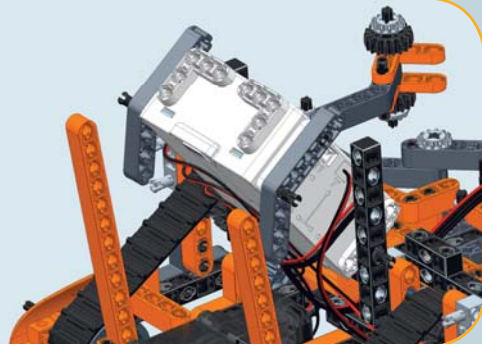
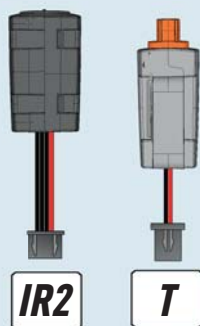
CONNECTE LES MOTEURS AU MODULE CENTRAL

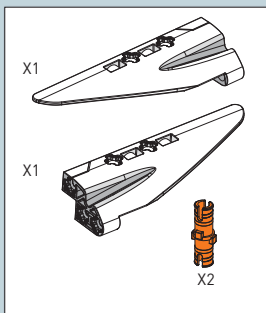
Orient le modèle comme sur l'image, puis connecte le moteur noir de gauche au port M1 et le moteur noir de droite au port M2. Connecte le moteur orange au port M3.



CONNECTE LES CAPTEURS AU MODULE CENTRAL

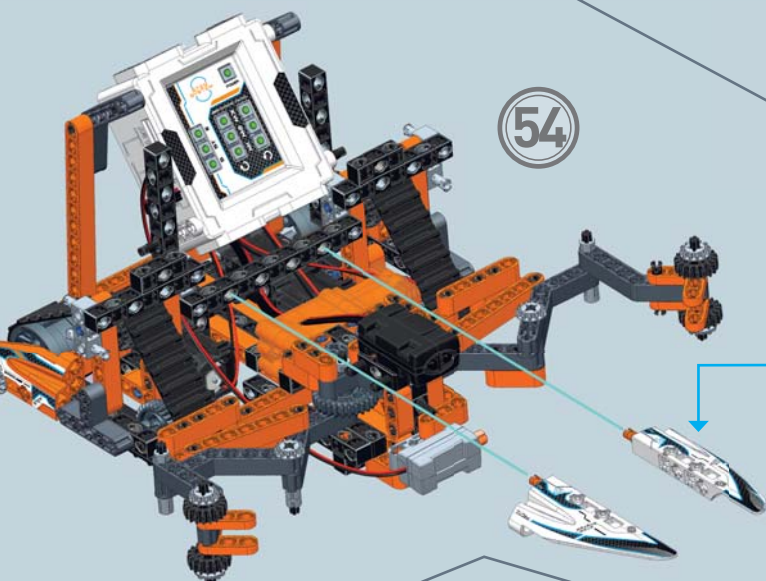
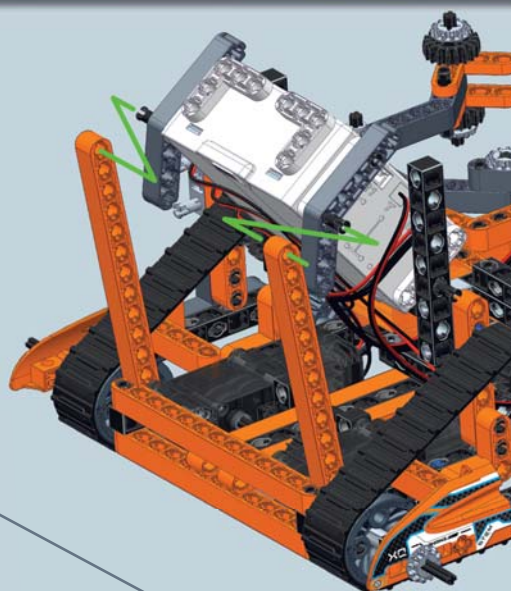
Connecte le capteur IR au port IR2. Connecte le capteur tactile au port T.



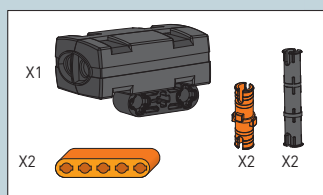
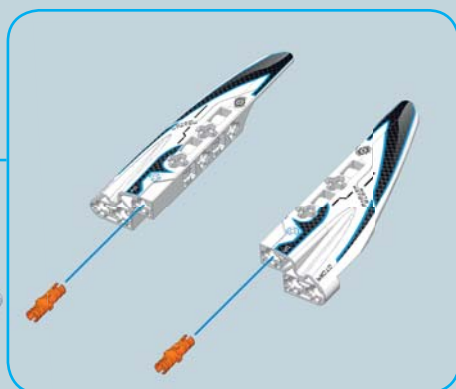


53

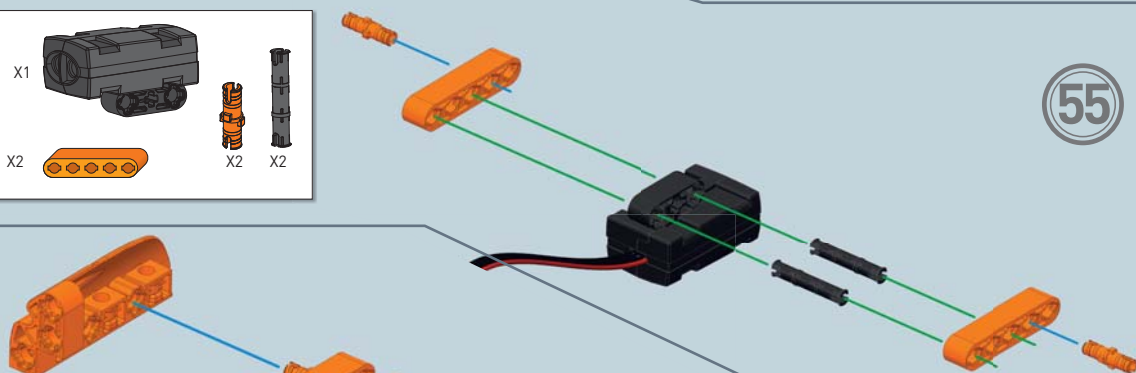
Fixe le module aux deux barres orange



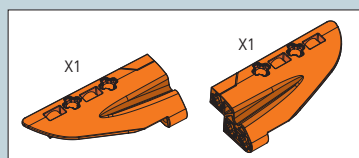
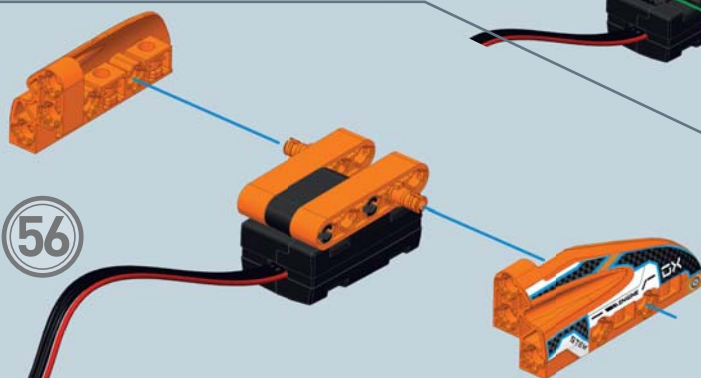
54

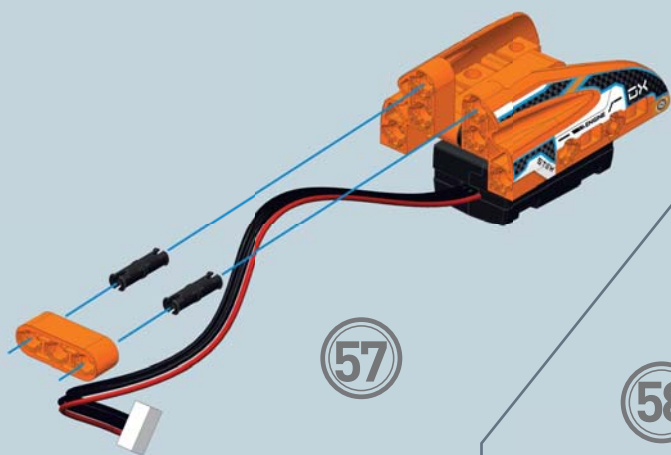


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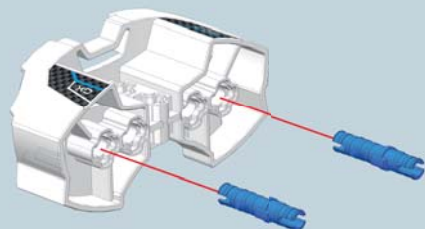
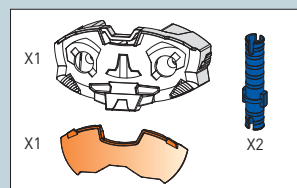


56

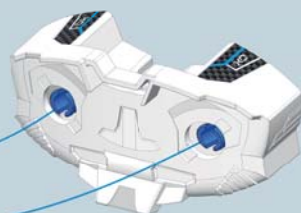




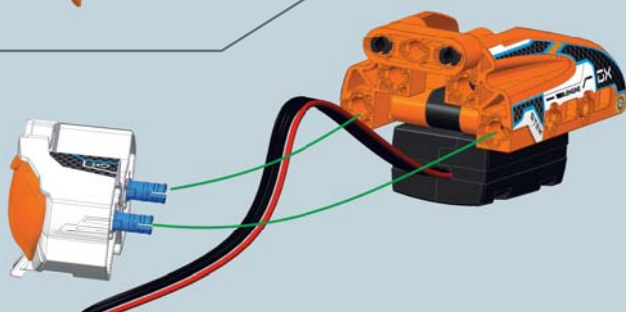
57



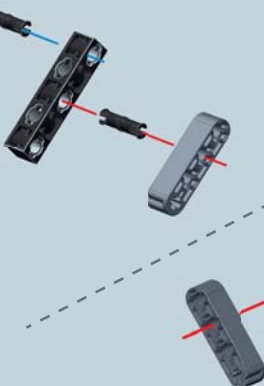
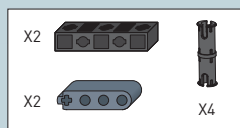
58



59

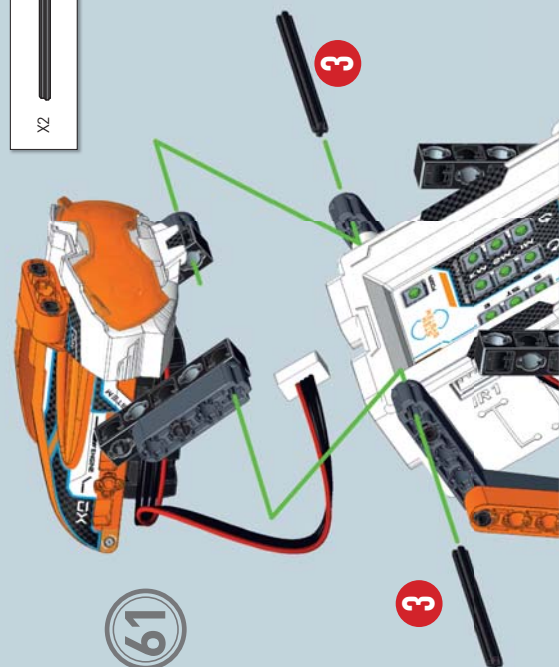


60





61

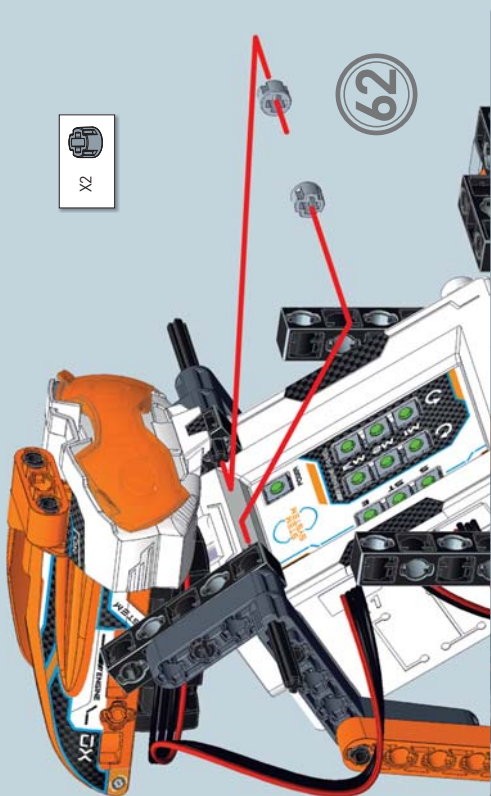


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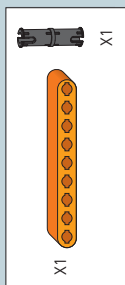
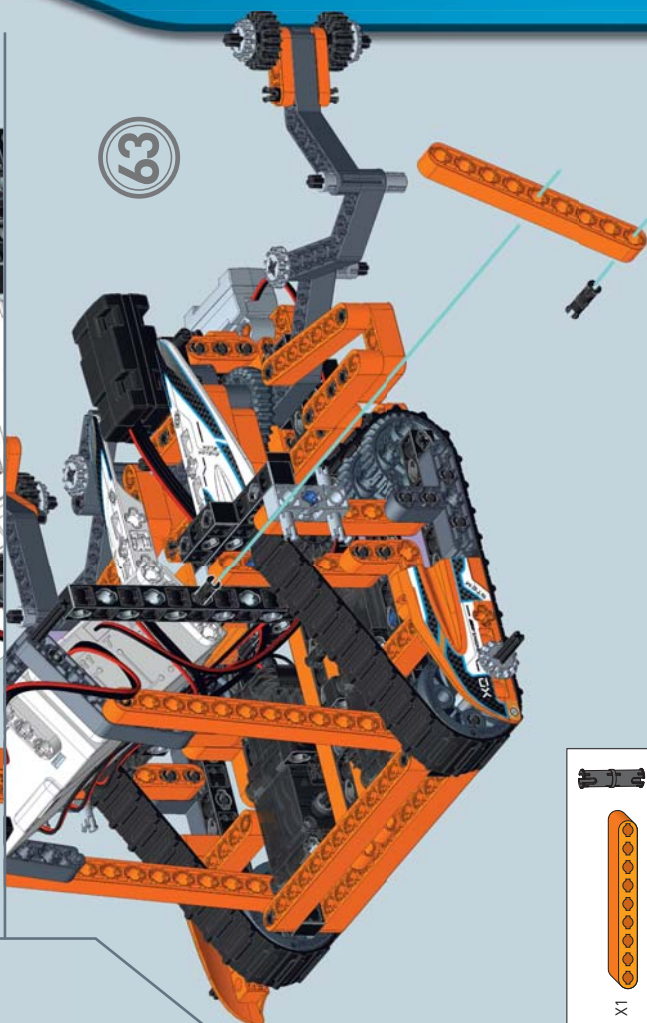
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62



63

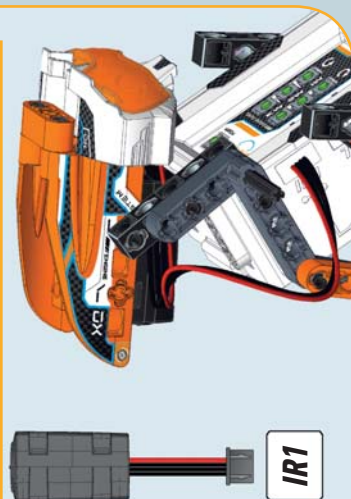


1:1

3

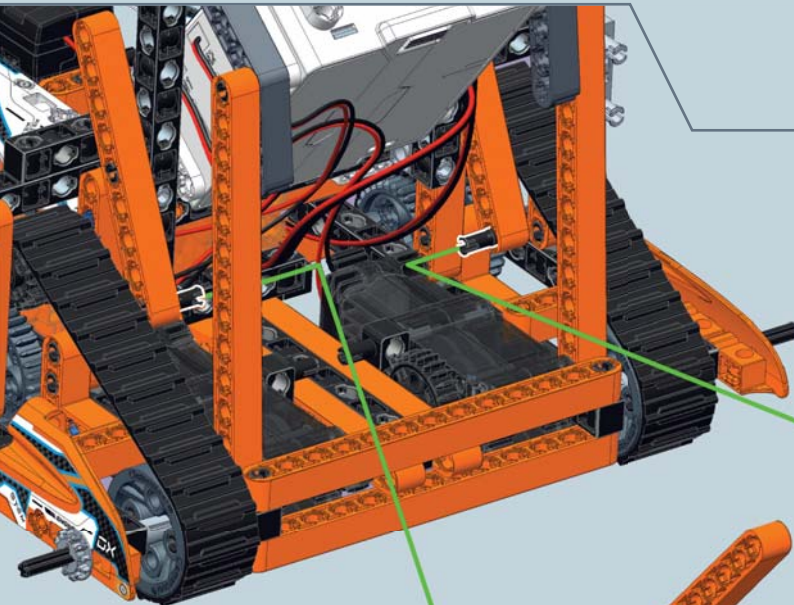
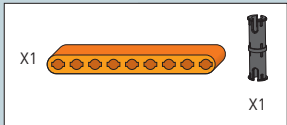
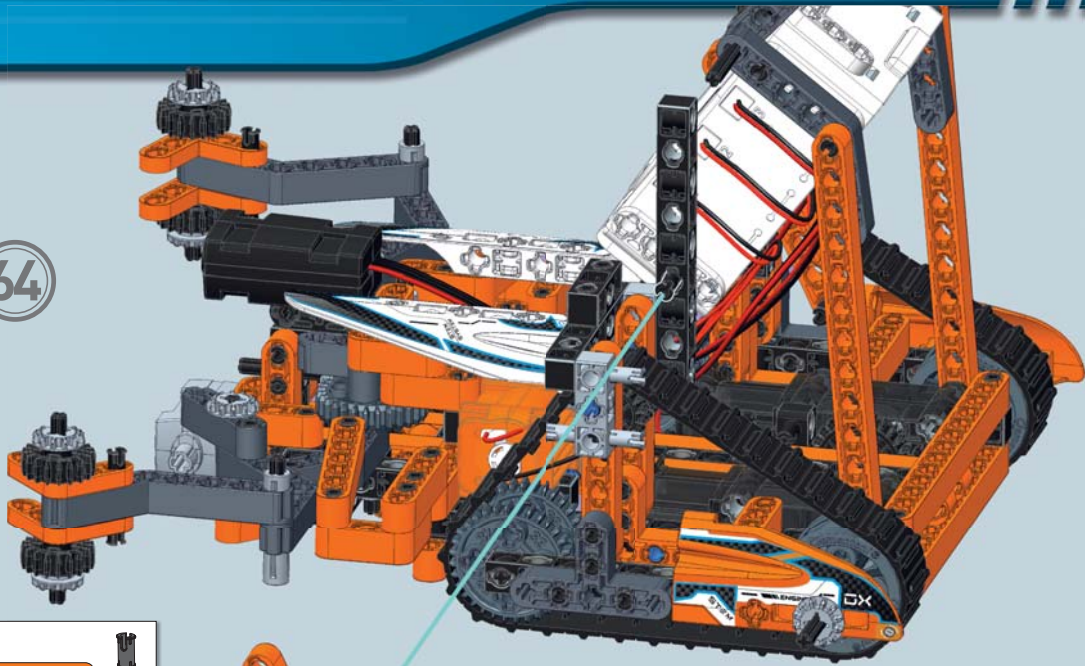
CONNECTE LE CAPTEUR AU MODULE CENTRAL

Connecte le capteur IR au port IR1.

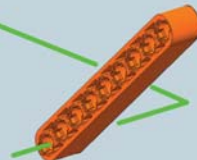


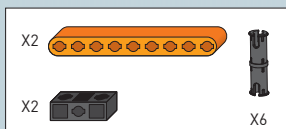
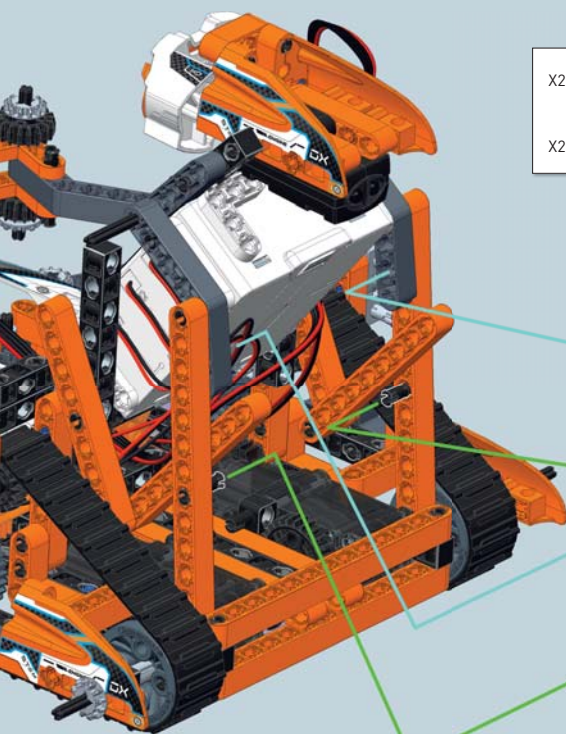
IR1

64

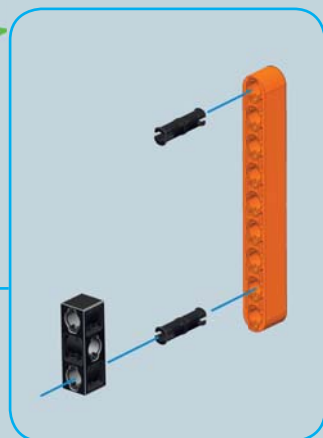
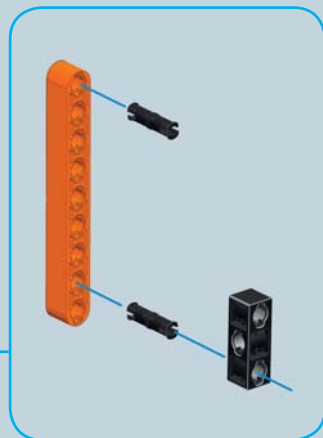


65

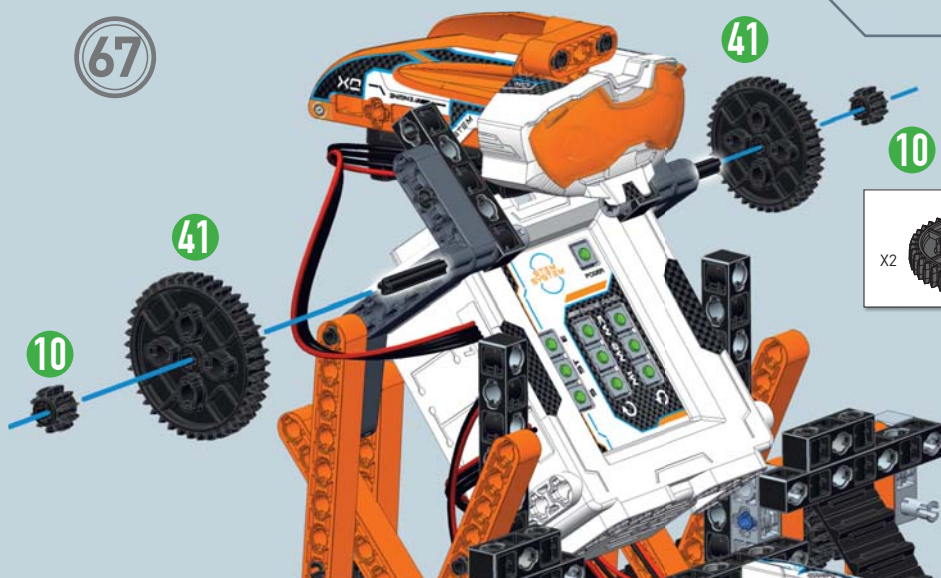


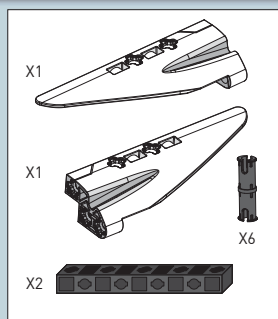


66

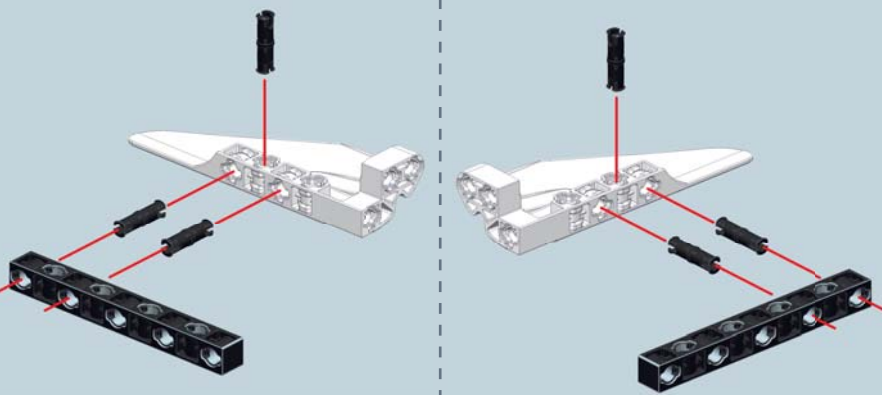


67

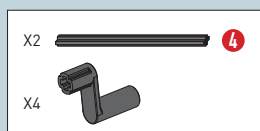
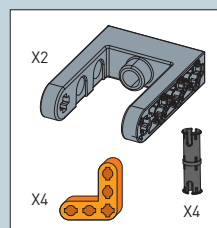
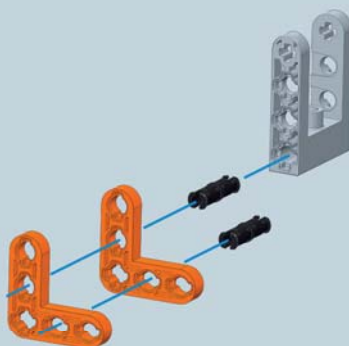
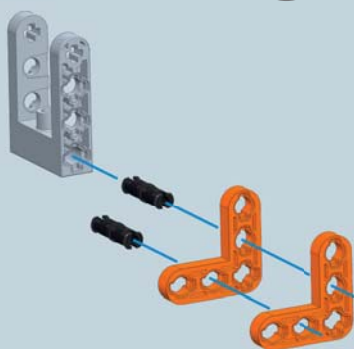




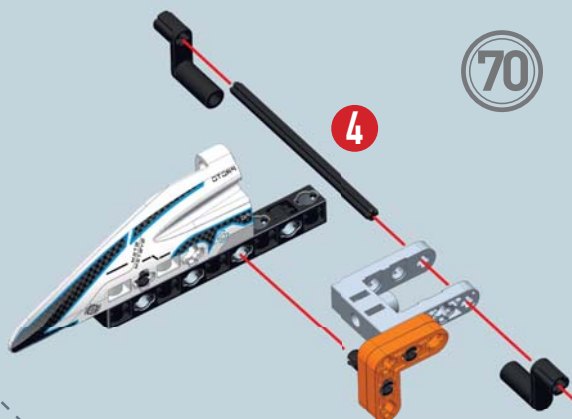
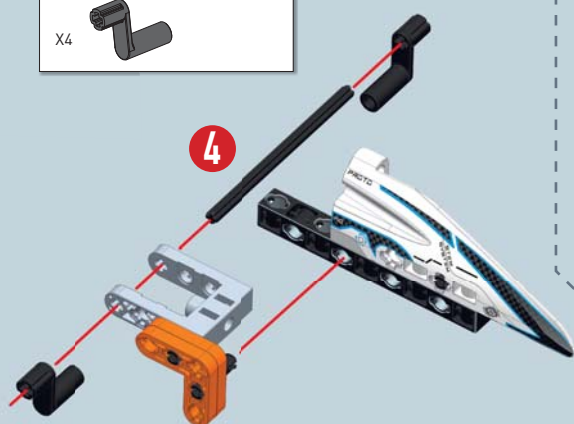
68



69



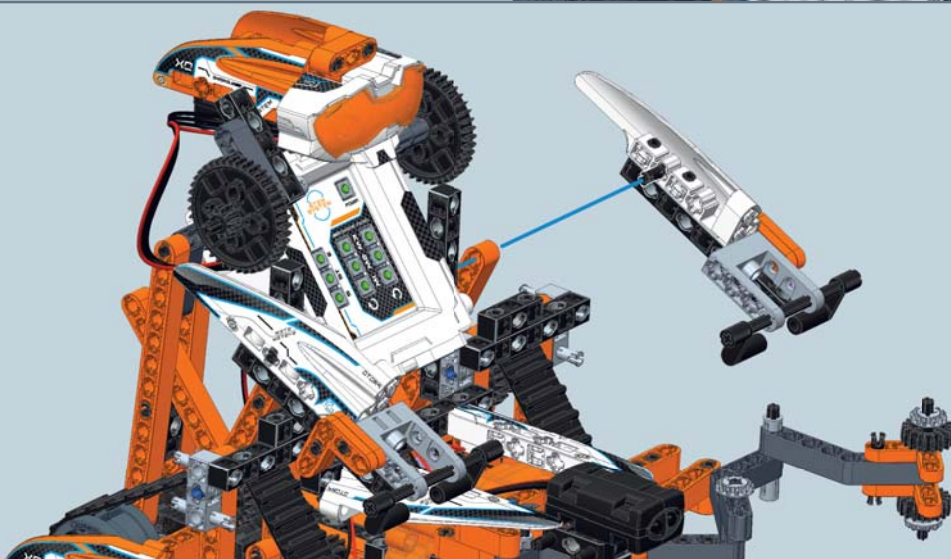
70



71



72



MODÈLE FINAL

